# Dynamics of algebraic solitons in the massive Thirring model

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# Section 1. The massive Thirring model (MTM)

The coupled mode equations

$$\begin{cases} i(u_t + u_x) + v = (\gamma_1 |u|^2 + \gamma_2 |v|^2)u \\ i(v_t - v_x) + u = (\gamma_2 |u|^2 + \gamma_1 |v|^2)v \end{cases}$$

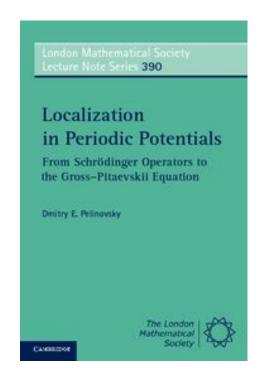
is a popular model for dynamics of two counter-propagating resonant waves across the periodic systems (photonics, Bose–Einstein condensation).

For instance, the Gross–Pitaevskii equation with  $2\pi$ -periodic, bounded, real-valued potential V(x):

$$i\partial_t \psi = -\partial_x^2 \psi + \varepsilon V(x)\psi \pm |\psi|^2 \psi,$$

is reduced asymptotically as  $\epsilon \to 0$  to the coupled mode equations for the superposition of two  $2\pi$ -antiperiodic waves (under Bragg's parameteric 1:2 resonance)

$$\psi(x,t) \sim \sqrt{\varepsilon} \left[ u(\varepsilon x, \varepsilon t) e^{\frac{i}{2}x} + v(\varepsilon x, \varepsilon t) e^{-\frac{i}{2}x} \right] e^{\frac{i}{4}t},$$



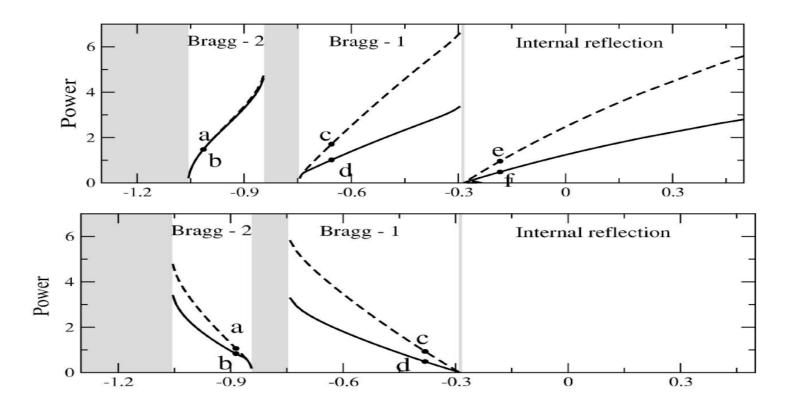
If  $\gamma_1 = 0$ , the system was introduced in quantum field theory by Thirring in 1958 as the relativistically invariant Dirac equation in one dimension, known now as the MTM in laboratory coordinates.

#### **Gap solitons**

For every  $\gamma_1, \gamma_2 > 0$ , there exist spatially decaying (localized) solutions called gap solitons (solitary waves) in the gaps of purely continuous spectrum of

$$\mathcal{L} := -\partial_x^2 + \varepsilon V(x), \quad \text{Dom}(\mathcal{L}) = H^2(\mathbb{R}) \subset L^2(\mathbb{R}), \qquad V(x + 2\pi) = V(x).$$

[Y.Kivshar, D.P., A. Sukhorukov (2004)] [A. Pankov (2005)] [M. Weinstein (2006)]



The decay rate is exponential except for the end points in each finite gap. Algebraic solitons attain the maximal power  $\int_{\mathbb{R}} |\psi|^2 dx$  in each family and the solutions are expressed explicitly within the coupled-mode theory.

#### **About exceptionality of the MTM**

The MTM in laboratory coordinates

$$\begin{cases} i(u_t + u_x) + v = |v|^2 u, \\ i(v_t - v_x) + u = |u|^2 v, \end{cases}$$

is the only example of the coupled-mode system which is relativistically invariant:

$$\begin{bmatrix} u(x,t) \\ v(x,t) \end{bmatrix} \mapsto \begin{bmatrix} \left(\frac{1-c}{1+c}\right)^{1/4} u \left(\frac{x+ct}{\sqrt{1-c^2}}, \frac{t+cx}{\sqrt{1-c^2}}\right) \\ \left(\frac{1+c}{1-c}\right)^{1/4} v \left(\frac{x+ct}{\sqrt{1-c^2}}, \frac{t+cx}{\sqrt{1-c^2}}\right) \end{bmatrix}, \quad c \in (-1,1).$$

It also has standard symmetries of translations in x, t, and arg(u) = arg(v).

MTM is integrable due to existence of the Lax pair [Mikhailov, 1976]:

$$\partial_x \varphi = L(u, v, \lambda) \varphi, \qquad \partial_t \varphi = A(u, v, \lambda) \varphi, \qquad \varphi(x, t) \in \mathbb{C}^2, \qquad \lambda \in \mathbb{C}.$$

See also [Orfanidis, 1976], [Kaup & Newell, 1977], [Barashenkov & Getmanov, 1989], [Villaroel, 1991], [Lee, 1994], [Zhou, 1995].

## About exceptionality of the algebraic solitons

One-soliton solutions are expressed in 1-parameter form:

$$\begin{bmatrix} u(x,t) \\ v(x,t) \end{bmatrix} = \sin \gamma \begin{bmatrix} \operatorname{sech} \left( x \sin \gamma + \frac{\mathrm{i}\gamma}{2} \right) \\ \operatorname{sech} \left( x \sin \gamma - \frac{\mathrm{i}\gamma}{2} \right) \end{bmatrix} e^{\mathrm{i}t \cos \gamma}, \quad \gamma \in (0,\pi)$$

with zero limit as  $\gamma \to 0$  and nonzero limit as  $\gamma \to \pi$ :

$$\gamma = \pi:$$
 
$$\left[ \begin{matrix} u(x,t) \\ v(x,t) \end{matrix} \right] = \left[ \begin{matrix} \dfrac{2}{1+2\mathrm{i}x} \\ \dfrac{1}{1-2\mathrm{i}x} \end{matrix} \right] e^{-\mathrm{i}t}, \qquad (u,v) \in L^2(\mathbb{R}).$$

The frequency of standing waves  $\omega=\cos\gamma\in(-1,1)$  takes values in the gap of the Dirac operator  $\mathcal{D}:=\begin{bmatrix}\mathrm{i}\partial_x&1\\1&-\mathrm{i}\partial_x\end{bmatrix}$  in  $L^2(\mathbb{R})$ , where  $\sigma(\mathcal{D})=(-\infty,-1]\cup[1,\infty)$ .

The algebraic soliton  $(\gamma = \pi)$  attains the maximal power  $Q(u,v) = \int_{\mathbb{R}} (|u|^2 + |v|^2) dx = 4\pi$  along the family.

# Section 2. Stability of algebraic solitons

For stability of exponential solitons, several analytical results are available:

- Orbital stability in  $H^1(\mathbb{R})$  via constrained minimization of energy: P. & Shimabukuro (2014)
- Orbital stability in  $L^2(\mathbb{R})$  via Bäcklund transformation: Contreras, P., & Shimabukuro (2016)
- Asymptotic stability via IST:
   P. & Saalmann (2019), He, Liu, & Qu (2024)

In the limit of algebraic solitons, all methods fail!

- There is no coercivity of the second variation from higher-order energy.
- Bäcklund transformation become trivial and generalizations do not help: [Guo, Ling, & Liu (2013)]
- Solvability of the IST is not justified for slowly decaying potentials.

# The only available result is from Klaus, P, & Rothos (2006)

Consider the Kaup–Newell spectral problem

$$\partial_x \varphi = \begin{bmatrix} -i\lambda^2 & \lambda w(x) \\ -\lambda \bar{w}(x) & i\lambda^2 \end{bmatrix} \varphi,$$

where |w(x)| = |u(x)| = |v(x)| in defined from the solution of the MTM. Assume that

$$|w(x)| \sim \frac{b}{|x|}$$
 as  $|x| \to \infty$  for some  $b > 0$ .

- $\lambda_0 = i$  is an embedded eigenvalue only if  $b > \frac{1}{2}$ . [b = 1 for algebraic soliton.]
- If  $\lambda_0 = i$  is an embedded eigenvalue, then its geometric multiplicity is one. Its algebraic multiplicity is N+1 only if  $b>N+\frac{1}{2}$ . [No examples were given.]
- Let  $w_0$  be the algebraic soliton and  $\epsilon w_1(x)$  be a perturbation with fixed profile  $w_1$ . For every  $\epsilon \neq 0$ , there exists a simple eigenvalue of the Lax spectrum in each quadrant of  $\mathbb C$  independently of the sign of  $\epsilon$  provided that  $w_1$  satisfies a non-degeneracy condition. [This suggests stability of an algebraic soliton.]

## Why is this surprising?

The Gardner (modified KdV) equation

$$u_t + 12uu_x + 6u^2u_x + u_{xxx} = 0$$

also has the algebraic soliton

$$u_0(x) = -\frac{4}{1+4x^2}.$$

It is associated with the embedded eigenvalue  $\lambda=i$  in the Zakharov–Shabat spectral problem

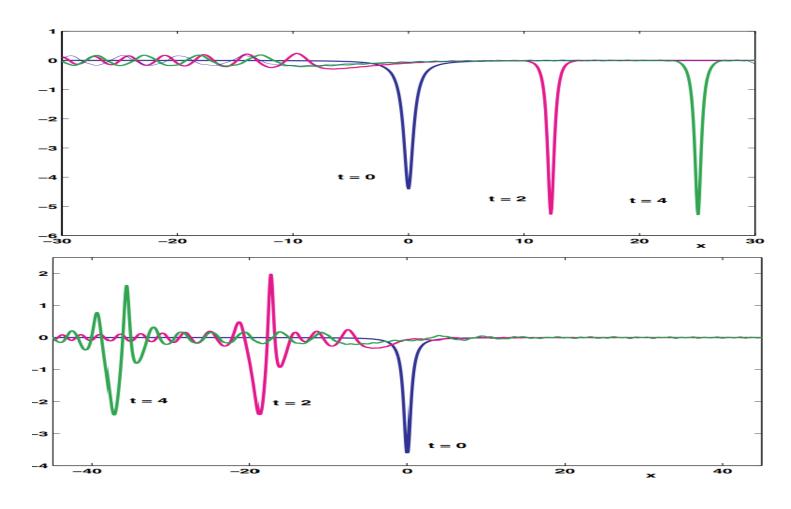
$$\partial_x \varphi = \begin{bmatrix} i\lambda & -1 - u(x) \\ 1 + u(x) & -i\lambda \end{bmatrix} \varphi.$$

Since the algebraic soliton is a nonzero minimum of conserved momentum  $Q(u) = \int_{\mathbb{R}} u^2 dx$  among exponential solitons, it is nonlinearly unstable.

Instability for similar mKdV and NLS models was shown in analysis papers: Fukaya & Hayashi (2021), Kfoury, Le Coz & Tsai (2022).

#### More results on instability of algebraic solitons in mKdV

- $\bullet$   $\lambda_0=i$  is an embedded eigenvalue of the Zakharov–Shabat spectral problem.
- Let  $\epsilon u_1(x)$  be a perturbation with fixed profile  $u_1$ . For every  $\epsilon \neq 0$ , we have either a simple eigenvalue  $\lambda = i + i\mathcal{O}(|\epsilon|^{2/3})$  or a symmetric pair of eigenvalues  $\lambda = i \pm \mathcal{O}(|\epsilon|^{2/3})$  depending on the sign of  $\epsilon$ . [P & Grimshaw (1997)]



## More results on instability of algebraic solitons in mKdV

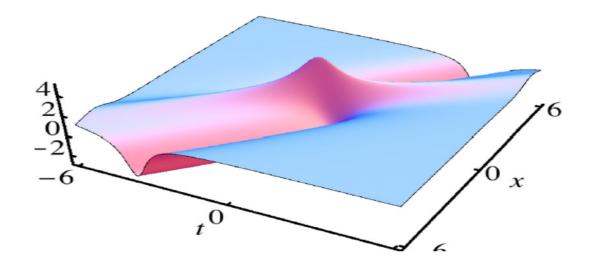
The instability of algebraic solitons can be shown from the rational solutions of the Gardner equation

$$u_t + 12uu_x + 6u^2u_x + u_{xxx} = 0.$$

A hierarchy of rational solutions is available in the form:

$$u_1(x) = -\frac{4}{1+4x^2}, \quad u_2(x,t) = \frac{P_4(x,t)}{P_6(x,t)}, \quad \dots$$

[Chowdury, Ankiewicz & Akhmediev (2016)], [Xing  $et\ al.\ (2017)$ ], [Bilman, Miller, Young (2025)]



The solution  $u_2$  suggests the instability of  $u_1$ :  $||u_2(\cdot,t)-u_1||_{L^2}$  grows in time t.

#### Section 3. Rational solutions of MTM

Consider the MTM in laboratory coordinates

$$\begin{cases} i(u_t + u_x) + v = |v|^2 u, \\ i(v_t - v_x) + u = |u|^2 v. \end{cases}$$

Rational solutions on nonzero background (rogue waves) were already constructed: Guo, Wang, Cheng, & He (2017) Ye, Bu, Pan, Chen, Mihalche, & Baronio (2021) Chen, Yang, & Feng (2023).

Surprisingly, rational solutions on the zero background have not been constructed for MTM.

We have constructed the second-order rational solution to the MTM: Jiaqi Han, Cheng He, & D.P. (2024)

#### Construction of the second-order rational solution

We use the bilinear formulation of the MTM from [Chen & Feng (2023)]:

$$u = \frac{g}{\overline{f}}, \qquad v = \frac{h}{f},$$

where

$$if(g_t + g_x) - ig(f_t + f_x) + h\bar{f} = 0, 
i\bar{f}(h_t - h_x) - ih(\bar{f}_t - \bar{f}_x) + gf = 0, 
i\bar{f}(f_x + f_t) - if(\bar{f}_t + \bar{f}_x) - |h|^2 = 0, 
if(\bar{f}_t - \bar{f}_x) - i\bar{f}(f_t - f_x) - |g|^2 = 0.$$

- The exponential 2-solitons are obtained with 8 parameters.
- Four parameters yields two eigenvalues  $\lambda_1 = \delta_1 e^{i\gamma_1}$  and  $\lambda_2 = \delta_2 e^{i\gamma_2}$  in the first quadrant of  $\mathbb{C}$ . Four more parameters are translational parameters.
- A limit to the algebraic 2-soliton solutions yields a soluton with 6 parameters:

$$\delta_1 \neq \delta_2, \qquad \gamma_1, \gamma_2 \to \pi.$$

• The limit  $\delta_1 \to \delta_2$  gives the algebraic double-soliton with 5 parameters.

#### The algebraic double-soliton

The algebraic double-soliton is expressed as the second-order rational solution

$$\begin{bmatrix} u(x,t) \\ v(x,t) \end{bmatrix} = \begin{bmatrix} \frac{4(-3+6\mathrm{i}x-12x^2-8\mathrm{i}x^3-12t(2x-\mathrm{i})-\mathrm{i}\beta)}{3+24\mathrm{i}x-24x^2+32\mathrm{i}x^3-16x^4+48t^2+2\beta(2x-\mathrm{i})} \\ \frac{4(-3-6\mathrm{i}x-12x^2+8\mathrm{i}x^3+12t(2x+\mathrm{i})+\mathrm{i}\beta)}{3-24\mathrm{i}x-24x^2-32\mathrm{i}x^3-16x^4+48t^2+2\beta(2x+\mathrm{i})} \end{bmatrix} e^{-\mathrm{i}t},$$

where  $\beta \in \mathbb{R}$  is a parameter in addition to  $c \in (-1,1)$  and  $x_0, t_0, \theta_0 \in \mathbb{R}$ .

The existence of the second-order rational solution suggestes the existence of a hierarchy of rational solutions in the form:

$$u_1(x,t) = \frac{2}{1+2ix}e^{-it}, \quad u_2(x,t) = \frac{P_3(x,t)}{P_4(x,t)}e^{-it}, \quad \dots$$

[Baofeng Feng, Jiaqi Han, Cheng He, & D.P. (2025) in progress]

# Properties of the algebraic double-soliton

1.  $u(\cdot,t), v(\cdot,t) \in C^{\omega}(\mathbb{R})$  for every  $t \in \mathbb{R}$  and  $\beta \in \mathbb{R}$ 

2. 
$$Q(u,v) = \int_{\mathbb{R}} (|u|^2 + |v|^2) dx = 8\pi = 2Q_{AS}$$
.

For the proofs, the bilinear formulation is very useful:

$$|u|^2 + |v|^2 = \frac{|g|^2 + |h|^2}{|f|^2} = 2i\left(\frac{f_x}{f} - \frac{\bar{f}_x}{\bar{f}}\right),$$

where

$$f = 16x^4 + 32ix^3 + 24x^2 + 24ix - 3 - 48t^2 - 2\beta(2x + i)$$

satisfies

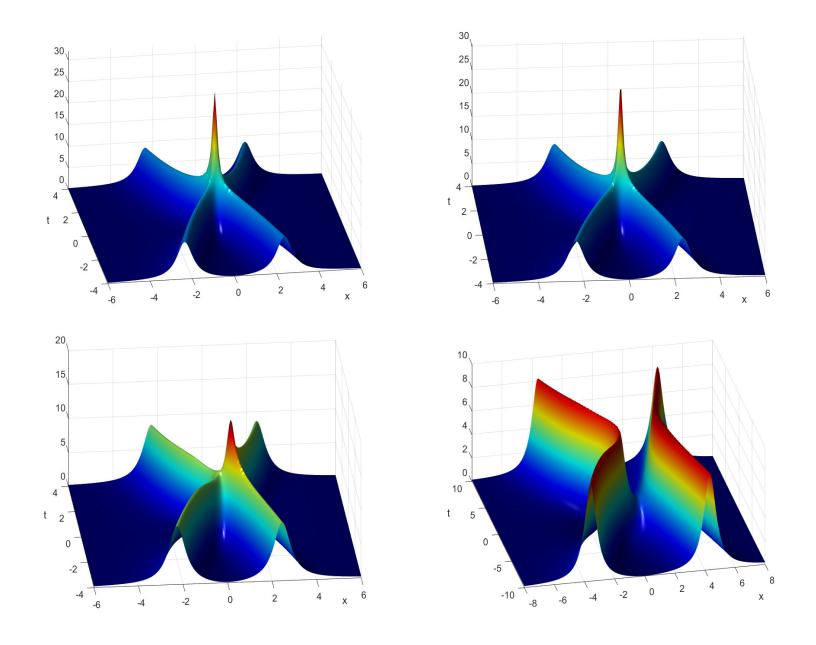
- f has no zeros on  $\mathbb R$  in x for every  $t \in \mathbb R$  and  $\beta \in \mathbb R$ .
- f has one root in  $\mathbb{C}_+$  and three roots in  $\mathbb{C}_-$ :  $N_+=1$ ,  $N_-=3$ .
- $f_x/f \bar{f}_x/\bar{f} = \mathcal{O}(|x|^{-2})$  as  $|x| \to \infty$ .

By the argument principle,

$$Q(u,v) = 4\pi(N_{-} - N_{+}) = 8\pi.$$

# Properties of the algebraic double-soliton

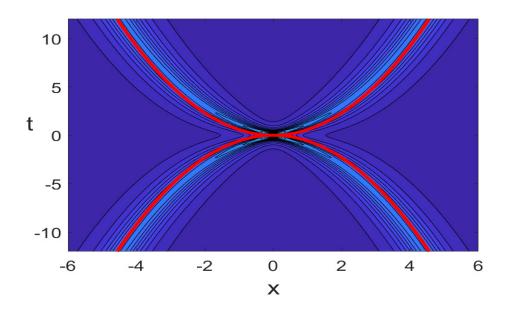
3. The solution suggests slow scattering of two identical algebraic solitons.



This suggests the nonlinear stability of a single algebraic soliton.

# Properties of the algebraic double-soliton

4. The two solitons move along the parabolas  $x^2 = \pm \sqrt{3t}$ .



5. The algebraic double-soliton corresponds to the double embedded eigenvalue  $\lambda_0=i$  in the Kaup–Newell spectral problem.

[Zhi-Qiang Li, P., Shou-Fu Tian (2025)]

This is in agreement with the result from [Klaus, P., Rothos (2006)]:

Algebraic multiplicity of  $\lambda_0 = i$  is N+1 only if  $b > N+\frac{1}{2}$ , where

$$|u(x)| \sim \frac{b}{|x|}$$
 as  $|x| \to \infty$  for some  $b > 0$ .

The algebraic double-soliton corresponds to b=2.

# Section 4. Construction of higher-order rational solutions.

The construction is done by the double-Wronskian formulas. In characteristic variables  $t=2(\xi+\eta)$  and  $x=2(\xi-\eta)$ , we have

$$\begin{cases} iu_{\xi} + 2v = 2|v|^2 u, \\ iv_{\eta} + 2u = 2|u|^2 v. \end{cases}$$

The bilinear transformation

$$u = \frac{g}{\overline{f}}, \qquad v = \frac{h}{f},$$

gives the bilinear equations

$$\begin{cases} iD_{\xi}(g \cdot f) + 2h\bar{f} = 0, \\ iD_{\eta}(h \cdot \bar{f}) + 2gf = 0, \\ iD_{\xi}(f \cdot \bar{f}) - 2h\bar{h} = 0, \\ iD_{\eta}(\bar{f} \cdot f) - 2g\bar{g} = 0. \end{cases}$$

[Baofeng Feng, Jiaqi Han, Cheng He, & D.P. (2025) in progress]

#### **Double-Wronskian solutions**

Let  $A \in \mathbb{M}^{2N \times 2N}$  be a complex-valued invertible matrix for  $N \in \mathbb{N}$ . Define two vectors  $\phi, \psi \in \mathbb{C}^{2N}$  from solutions of the linear equations

$$\begin{cases} \partial_{\xi} \phi = iA\phi, \\ \partial_{\eta} \phi = iA^{-1}\phi, \end{cases} \quad \text{and} \quad \begin{cases} \partial_{\xi} \psi = -iA\psi, \\ \partial_{\eta} \psi = -iA^{-1}\psi, \end{cases}$$

Furthermore, relate  $\psi=S\bar{\phi}$ , where  $S=\sqrt{-A}\in\mathbb{M}^{2N\times 2N}$ . Then, the bilinear equations are solved by

$$\begin{cases}
f = |\phi', \phi'', \dots, \phi^{(N)}, \psi, \psi', \dots, \psi^{(N-1)}| \\
g = |\phi, \phi', \dots, \phi^{(N)}, \psi', \psi'', \dots, \psi^{(N-1)}| \\
h = i^{N+1} |S| |\phi, \phi', \dots, \phi^{(N)}, \psi, \psi', \dots, \psi^{(N-2)}|.
\end{cases}$$

Higher-order rational solutions are obtained from the N-multiple e-value  $\lambda_0 = i$ :

$$A = \begin{bmatrix} -1 & 0 & 0 & \dots & 0 & 0 \\ 1 & -1 & 0 & \dots & 0 & 0 \\ 0 & 1 & -1 & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \dots & 1 & -1 \end{bmatrix}, \quad S = \begin{bmatrix} 1 & 0 & 0 & \dots & 0 & 0 \\ -\frac{1}{2} & 1 & 0 & \dots & 0 & 0 \\ -\frac{1}{2^3} & -\frac{1}{2} & 1 & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \dots & -\frac{1}{2} & 1 \end{bmatrix}.$$

## Properties of the higher-order rational solutions

For each integer N, we have

$$u = \frac{Q_N(x,t)}{\bar{P}_N(x,t)}e^{-it}, \quad v = \frac{R_N(x,t)}{P_N(x,t)}e^{-it},$$

where  $P_N$  is a polynomial in x of degree  $N^2$  and  $Q_N$ ,  $R_N$  are of degree  $N^2-1$ .

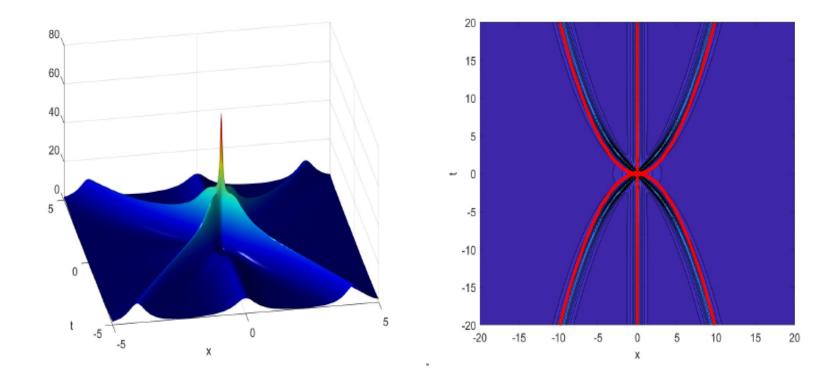
This follows from the leading-order behavior of f, g, and h, if we can prove that

For  $1 \leq N \leq 10$ , we confirmed the formula

$$\Delta_N = \frac{2^N (-1)^N}{1^{2N-1} 3^{2N-3} \dots (2N-3)^3 (2N-1)^1}$$

but cannot prove it for now. This computation yields  $|u(x)| \sim \frac{b}{|x|}$  with b = N for N-multiple eigenvalue  $\lambda_0 = i$  in agreement with [Klaus, P., Rothos (2006)].

## The example of N=3



The separation distance grows as  $x^2 = \sqrt{9 + 6\sqrt{6}}|t|$  and the mass  $Q(u,v) = 12\pi$ .

Generally, we conjecture for every integer  ${\cal N}$  that

$$Q(u,v) = \int_{\mathbb{R}} (|u|^2 + |v|^2) dx = 4\pi N$$

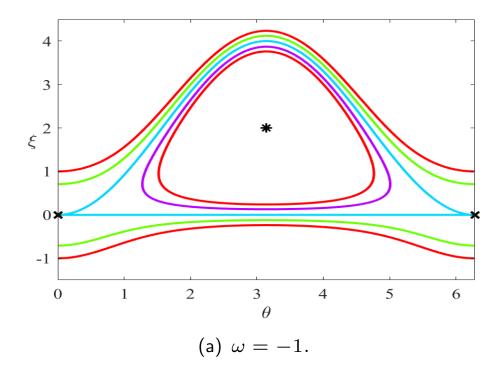
and that  $x^2 \sim |t|$  as  $|t| \to \infty$ .

# Section 5. Algebraic solitons in the limit of periodic solutions

Here is the phase plane for the standing wave solutions

$$u(x,t) = U(x)e^{-i\omega t}, \qquad v(x,t) = \bar{U}(x)e^{-i\omega t},$$

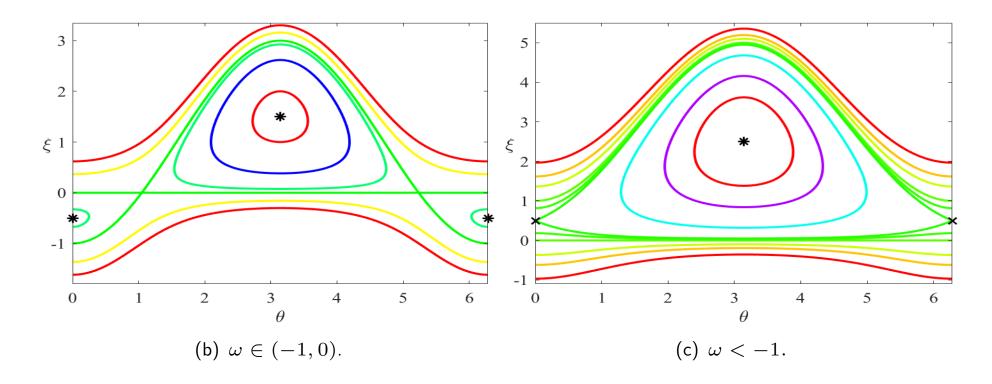
with 
$$U(x) = \sqrt{\xi(x)}e^{\frac{i}{2}\theta(x)}$$
.



Algebraic soliton corresponds to the degenerate homoclinic orbit for  $\omega=-1$ .

# Algebraic solitons between two different exponential solitons

Algebraic soliton at  $\omega=-1$  is located in between exponential soliton for  $\omega\in(-1,1)$  and solitons on the constant background for  $\omega<-1$ .



[Shikun Cui, P. (2025)]

## **Squared eigenfunction relation**

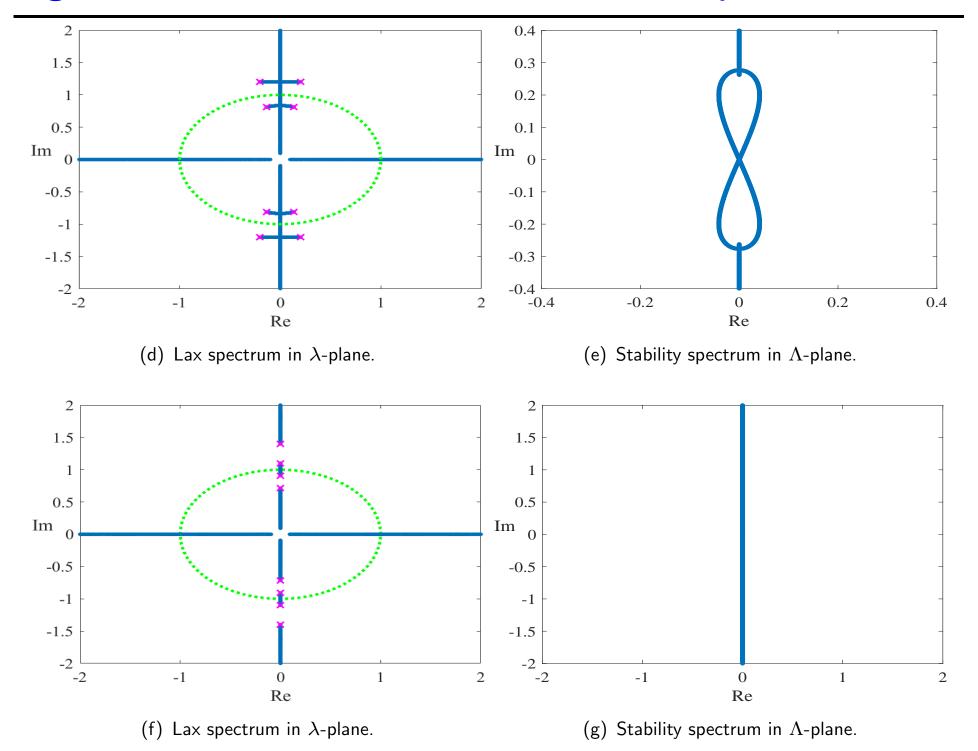
Linear stability is solved by the squared eigenfunctions [Kaup-Lakoba (1996)]

$$\Lambda = \pm i\sqrt{P(\lambda)}, \quad P(\lambda) = \frac{1}{4}\left(\lambda^2 + \frac{1}{\lambda^2} - 2\omega\right)^2 - b,$$

where b is the conserved energy for the spatial profile U(x) and  $\lambda \in \mathbb{C}$  belongs to the Lax spectrum with bounded eigenfunctions

$$\partial_x \varphi = L(u, v, \lambda) \varphi, \qquad \varphi \in L^{\infty}(\mathbb{R}, \mathbb{C}^2)$$

# Algebraic soliton between unstable and stable periodic waves



#### **Section 6. Conclusion**

There are multiple evidences of stability of algebraic solitons in the MTM system:

- Persistence with respect to perturbations. [Klaus, P, & Rothos (2006)]
- Persistence in rational solutions. [Cheng, Han, P. (2024)]
- Linear stability with squared eigenfunctions. [Cui, P. (2025)]

However, there exists no mathematically rigorous proof of the nonlinear stability of algebraic solitons for the MTM system.

A similar question is open for the derivative NLS equation.