

Bäcklund transformation and L^2 -stability of NLS solitons

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Reference: arXiv:1011.5922

IMACS conference on nonlinear waves, *Athens GA*, April 6, 2011

Introduction

We would like to consider asymptotic stability of solitons to 1D NLS equation,

$$iu_t = -u_{xx} + V(x)u - |u|^{2p}u, \quad \text{for } (t, x) \in \mathbb{R} \times \mathbb{R}.$$

where $V : \mathbb{R} \rightarrow \mathbb{R}$ is a trapping potential and $p > 0$.

Assume existence of solitons $u(x, t) = \phi(x)e^{-i\omega t - i\theta}$ with some $\omega \in \mathbb{R}$ and arbitrary $\theta \in \mathbb{R}$. Assume that the solitons are orbitally stable in $H^1(\mathbb{R})$, that is, for any $\epsilon > 0$ there is a $\delta(\epsilon) > 0$, such that if $\|u(0) - \phi\|_{H^1} \leq \delta(\epsilon)$ then

$$\inf_{\theta \in \mathbb{R}} \|u(t) - e^{-i\theta}\phi\|_{H^1} \leq \epsilon,$$

for all $t > 0$.

- Buslaev and Sulem (2003) proved asymptotic stability for the case $p \geq 4$.
- Cuccagna (2008) and Mizumachi (2008) improved the results with Strichartz analysis for the case $p \geq 2$.
- No results are available for $p = 1$ even if $V(x) \equiv 0$.

Cubic NLS equation

We shall consider the cubic NLS equation,

$$iu_t + u_{xx} + 2|u|^2u = 0 \quad \text{for } (t, \mathbf{x}) \in \mathbb{R} \times \mathbb{R}. \quad (\text{NLS})$$

Properties of the cubic NLS equation:

- (NLS) is integrable Hamiltonian system and has infinitely many conservation laws (Zakharov and Shabat, 1972). First conserved quantities

$$\mathbf{N} := \|u(t, \cdot)\|_{L^2} \quad \text{and} \quad \mathbf{E} := \frac{1}{2} \int_{\mathbb{R}} (|u_x(t, \mathbf{x})|^2 - |u(t, \mathbf{x})|^4) dx$$

do not depend on t if $u(t, \mathbf{x})$ is a solution of (NLS).

- (NLS) is locally well-posed in L^2 (Tsutsumi, 1987). Thanks to L^2 conservation, it is globally well-posed in L^2 .
- (NLS) is also well-posed in H^k for any $k \in \mathbb{N}$ (Kato, 1987).

Soliton solutions

- (NLS) has a 4-parameter family of 1-solitons

$$Q_{k,v}(t + t_0, x + x_0) = Q_k(x - vt) e^{ivx/2 + i(k^2 - v^2/4)t},$$

where

$$Q_k(x) = k \operatorname{sech}(kx), \quad k > 0, \quad v \in \mathbb{R}, \quad x_0 \in \mathbb{R}, \quad t_0 \in \mathbb{R}.$$

- Q_k is a minimizer of $E|_{\mathcal{M}}$, where

$$\mathcal{M} = \{u \in H^1(\mathbb{R}), \|u\|_{L^2} = \|Q_k\|_{L^2}\},$$

hence, it is orbitally stable (Cazenave and Lions, 1982).

- Colliander-Keel-Staffilani-Takaoka-Tao, 2003 : metastability and polynomial growth of solutions around solitons in H^s for $0 < s < 1$.
- **Questions:** Is 1-soliton orbitally stable in L^2 ?
Is 1-soliton asymptotically stable in H^1 or L^2 ?

Bäcklund transformation of (NLS)

A Bäcklund transformation is a mapping between two solutions of the same (or different) equations. It was originally found for the sine-Gordon equation by Bianchi (1879) and Bäcklund (1882) but was extended to KdV, KP, Benjamin-Ono, Toda, and other integrable equations in 1970s.

For (NLS), let η be a constant and consider the Lax operator system,

$$\partial_x \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} = \begin{pmatrix} \eta & \mathbf{q} \\ -\bar{\mathbf{q}} & -\eta \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix}, \quad (\text{Lax1})$$

$$\partial_t \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} = \begin{pmatrix} 2\eta^2 + |\mathbf{q}|^2 & \partial_x \mathbf{q} + 2\eta \mathbf{q} \\ \partial_x \bar{\mathbf{q}} - 2\eta \bar{\mathbf{q}} & -2\eta^2 - |\mathbf{q}|^2 \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix}. \quad (\text{Lax2})$$

(Lax1) and (Lax2) are compatible if $i\mathbf{q}_t + \mathbf{q}_{xx} + 2|\mathbf{q}|^2\mathbf{q} = \mathbf{0}$.

Let $\mathbf{q}(\mathbf{t}, \mathbf{x})$ be a solution of (NLS) and (ψ_1, ψ_2) be a solution of (Lax1)–(Lax2). Suppose

$$\mathbf{Q} = -\mathbf{q} - \frac{4\eta\psi_1\bar{\psi}_2}{|\psi_1|^2 + |\psi_2|^2}.$$

Then $\mathbf{Q}(\mathbf{t}, \mathbf{x})$ is a solution of (NLS). (Chen'74, Konno and Wadati '75)

Bäcklund transformation $0 \rightarrow 1$ soliton

- Let $\eta = \frac{1}{2}$ and $\mathbf{q} \equiv \mathbf{0}$. Then,

$$\psi_1 = e^{(x+it)/2}, \quad \psi_2 = -e^{-(x+it)/2} \Rightarrow \mathbf{Q} = e^{it} \operatorname{sech}(x).$$

- Let $\Psi_1 = \frac{\bar{\psi}_2}{|\psi_1|^2 + |\psi_2|^2}$ and $\Psi_2 = \frac{\psi_1}{|\psi_1|^2 + |\psi_2|^2}$. Then (Ψ_1, Ψ_2) satisfy the Lax operator system:

$$\partial_x \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix} = \begin{pmatrix} \eta & \mathbf{Q} \\ -\bar{\mathbf{Q}} & -\eta \end{pmatrix} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix}, \quad (\text{Lax}'1)$$

$$\partial_t \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix} = \begin{pmatrix} 2\eta^2 + |\mathbf{Q}|^2 & \partial_x \mathbf{Q} + 2\eta \mathbf{Q} \\ \partial_x \bar{\mathbf{Q}} - 2\eta \bar{\mathbf{Q}} & -2\eta^2 - |\mathbf{Q}|^2 \end{pmatrix} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix}. \quad (\text{Lax}'2)$$

- If $\mathbf{Q} = e^{it} \operatorname{sech}(x)$, then $\eta = \frac{1}{2}$ is an eigenvalue of (Lax'1) with

$$\Psi_1 = -e^{(-x+it)/2} \operatorname{sech}(x), \quad \Psi_2 = e^{(x+it)/2} \operatorname{sech}(x).$$

Applications of Bäcklund transformation

We show Lyapunov stability of **1**-solitons in the L^2 class.

$$\begin{array}{ccc} \mathbf{Q}(0, \mathbf{x}) & \xrightarrow{NLS} & \mathbf{Q}(t, \mathbf{x}) \\ BT \downarrow & & \uparrow BT \\ \mathbf{q}_0(\mathbf{x}) & \xrightarrow{NLS} & \mathbf{q}(t, \mathbf{x}) \end{array}$$

$\|\mathbf{Q}(0, \cdot) - \mathbf{Q}_1\|_{L^2}$ is small,

$\|\mathbf{q}(t)\|_{L^2} = \|\mathbf{q}(0)\|_{L^2}$ is small.

- Merle and Vega (2003) used the Miura transformation to prove asymptotic stability of KdV solitons in L^2 .
- Mizumachi and Tzvetkov (2011) applied the same transformation to prove L^2 -stability of line solitons in the KP-II equation under periodic transverse perturbations.
- Mizumachi and Pego (2008) used Backlund transformation to prove asymptotic stability of Toda lattice solitons.
- Hoffman and Wayne (2009) extended this result to two and \mathbf{N} solitons.

Theorem

Fix $\mathbf{k}_0 > \mathbf{0}$. Let $\mathbf{u}(t, \mathbf{x})$ be a solution of (NLS) in the class

$$\mathbf{u} \in \mathbf{C}(\mathbb{R}; L^2(\mathbb{R})) \cap L^8_{loc}(\mathbb{R}; L^4(\mathbb{R})).$$

There exist $\mathbf{C}, \varepsilon > \mathbf{0}$ such that if $\|\mathbf{u}(\mathbf{0}, \cdot) - \mathbf{Q}_{\mathbf{k}_0}\|_{L^2} < \varepsilon$, then there exist $\mathbf{k}, \mathbf{v}, \mathbf{t}_0, \mathbf{x}_0$ such that

$$\sup_{t \in \mathbb{R}} \|\mathbf{u}(t + \mathbf{t}_0, \cdot + \mathbf{x}_0) - \mathbf{Q}_{\mathbf{k}, \mathbf{v}}\|_{L^2} + |\mathbf{k} - \mathbf{k}_0| + |\mathbf{v}| + |\mathbf{t}_0| + |\mathbf{x}_0| \leq \mathbf{C} \|\mathbf{u}(\mathbf{0}, \cdot) - \mathbf{Q}_{\mathbf{k}_0}\|_{L^2}.$$

- In KdV, perturbations of **1**-solitons can cause logarithmic growth of the phase shift due to collisions with small solitary waves (Martel and Merle, 2005). For the cubic NLS, a solution remains in the neighborhood of a **1**-soliton for all the time.

Outline of the proof

For the sake of simplicity, we consider $\mathbf{k}_0 = \mathbf{1}$ ($\eta = \frac{1}{2}$).

$$\begin{array}{ccc} \mathbf{Q}(\mathbf{0}, \mathbf{x}) & \xrightarrow{NLS} & \mathbf{Q}(\mathbf{t}, \mathbf{x}) \\ BT \downarrow & & \uparrow BT \\ \mathbf{q}_0(\mathbf{x}) & \xrightarrow{NLS} & \mathbf{q}(\mathbf{t}, \mathbf{x}) \end{array} \quad \begin{array}{l} \|\mathbf{Q}(\mathbf{0}, \cdot) - \mathbf{Q}_1\|_{L^2} \text{ is small,} \\ \|\mathbf{q}(\mathbf{t})\|_{L^2} = \|\mathbf{q}(\mathbf{0})\|_{L^2} \text{ is small.} \end{array}$$

- Step 1: From a nearly $\mathbf{1}$ -soliton to a nearly zero solution at $\mathbf{t} = \mathbf{0}$.
- Step 2: Time evolution of the nearly zero solution for $\mathbf{t} \in \mathbb{R}$.
- Step 3: From the nearly zero solution to the nearly $\mathbf{1}$ -soliton for $\mathbf{t} \in \mathbb{R}$.
- Step 4: Approximation arguments in $\mathbf{H}^3(\mathbb{R})$ to control modulations of parameters of $\mathbf{1}$ -solitons for all $\mathbf{t} \in \mathbb{R}$.

Step 1

At $t = 0$, Q is close to $Q_1 = \operatorname{sech}(x)$ and η is close to $\frac{1}{2}$. If $Q = Q_1$ and $\eta = \frac{1}{2}$, then the Lax operator

$$\partial_x \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix} = \begin{pmatrix} \eta & Q \\ -\bar{Q} & -\eta \end{pmatrix} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix},$$

has two linearly independent solutions

$$\begin{bmatrix} -e^{-x/2} \\ e^{x/2} \end{bmatrix} \operatorname{sech}(x), \quad \begin{bmatrix} (e^x + 2(1+x)e^{-x})e^{x/2} \\ (e^{-x} - 2xe^x)e^{-x/2} \end{bmatrix} \operatorname{sech}(x).$$

If

$$q := -Q_1 + \frac{-4\eta\Psi_1\bar{\Psi}_2}{|\Psi_1|^2 + |\Psi_2|^2},$$

then $q = 0$ follows from the first solution and

$$q(x) = \frac{2xe^{2x} + (4x^2 + 4x - 1) - 2x(1+x)e^{-2x}}{\cosh(3x) + 4(1+x+x^2)\cosh(x)} - \operatorname{sech}(x)$$

follows from the second solution.

Step 1

- If $\|Q - Q_1\|_{L^2}$ is small, then there exists $\eta = (k + iv)/2$ and $\Psi \in H^1(\mathbb{R})$ such that

$$|k - 1| + |v| + \|\Psi - \Psi_1\|_{H^1} \leq C\|Q - Q_1\|_{L^2}.$$

- If

$$q := -Q - \frac{2k\Psi_1\bar{\Psi}_2}{|\Psi_1|^2 + |\Psi_2|^2},$$

then $q \in L^2(\mathbb{R})$ and

$$\begin{aligned} \|q_0\|_{L^2} &\leq \|Q - Q_1\|_{L^2} + \left\| Q_1 + \frac{2k\Psi_1\bar{\Psi}_2}{|\Psi_1|^2 + |\Psi_2|^2} \right\|_{L^2} \\ &\lesssim \|Q - Q_1\|_{L^2}. \end{aligned}$$

- Moreover, if $Q \in H^3(\mathbb{R})$, then $q \in H^3(\mathbb{R})$.

Steps 2 and 3

If $\mathbf{q}(\mathbf{0}, \cdot) \in H^3(\mathbb{R})$ and $\|\mathbf{q}(\mathbf{0}, \cdot)\|_{L^2}$ is small, then $\mathbf{q} \in C(\mathbb{R}, H^3(\mathbb{R}))$ and $\|\mathbf{q}(\mathbf{t}, \cdot)\|_{L^2}$ remains small for all $\mathbf{t} \in \mathbb{R}$.

If $\mathbf{q} \equiv \mathbf{0}$, then $\{(\mathbf{e}^{x/2}, \mathbf{0}), (\mathbf{0}, \mathbf{e}^{-x/2})\}$ is a fundamental system of (Lax1).
If $\mathbf{q} = \mathbf{q}(\mathbf{0}, \mathbf{x})$ is small in L^2 , there exist bounded solutions $\mathbf{e}^{x/2} \vec{\varphi}(\mathbf{x}) = \mathbf{e}^{x/2}(\varphi_1(\mathbf{x}), \varphi_2(\mathbf{x}))$ and $\mathbf{e}^{-x/2} \vec{\chi}(\mathbf{x}) = \mathbf{e}^{-x/2}(\chi_1(\mathbf{x}), \chi_2(\mathbf{x}))$ of (Lax1), where

$$\begin{cases} \varphi_1' = \mathbf{q}\varphi_2, \\ \varphi_2' = -\bar{\mathbf{q}}\varphi_1 - \varphi_2, \end{cases}, \quad \begin{cases} \chi_1' = \chi_1 + \mathbf{q}\chi_2, \\ \chi_2' = -\bar{\mathbf{q}}\chi_1, \end{cases}$$
$$\lim_{x \rightarrow \infty} \varphi_1(\mathbf{x}) = 1, \quad \lim_{x \rightarrow -\infty} \chi_2(\mathbf{x}) = -1.$$

A bounded solution (φ_1, φ_2) satisfies

$$\begin{cases} \varphi_1(\mathbf{x}) = 1 - \int_x^\infty \mathbf{q}(\mathbf{y})\varphi_2(\mathbf{y})d\mathbf{y} =: T_1(\varphi_1, \varphi_2)(\mathbf{x}), \\ \varphi_2(\mathbf{x}) = - \int_{-\infty}^x \mathbf{e}^{-(x-y)} \bar{\mathbf{q}}(\mathbf{y})\varphi_1(\mathbf{y})d\mathbf{y} =: T_2(\varphi_1, \varphi_2)(\mathbf{x}). \end{cases}$$

Step 3

- If $\|\mathbf{q}\|_{L^2}$ is small, then $\mathbf{T} = (\mathbf{T}_1, \mathbf{T}_2)$ is a contraction mapping on $L^\infty \times (L^\infty \cap L^2)$ and

$$\begin{aligned}\|\varphi_1 - \mathbf{1}\|_{L^\infty} + \|\varphi_2\|_{L^\infty \cap L^2} &\leq \mathbf{C}\|\mathbf{q}\|_{L^2}, \\ \|\chi_1\|_{L^\infty \cap L^2} + \|\chi_2 + \mathbf{1}\|_{L^\infty} &\leq \mathbf{C}\|\mathbf{q}\|_{L^2}.\end{aligned}$$

- If $\mathbf{q}(t, \mathbf{x})$ is an $H^3(\mathbb{R})$ -solution of (NLS), then

$$\begin{aligned}\sup_t (\|\varphi_1(t, \cdot) - e^{it/2}\|_{L^\infty} + \|\varphi_2(t, \cdot)\|_{L^2 \cap L^\infty}) &\leq \mathbf{C}\|\mathbf{q}(0, \cdot)\|_{L^2}, \\ \sup_t (\|\chi_1(t, \cdot)\|_{L^2 \cap L^\infty} + \|\chi_2(t, \cdot) + e^{-it/2}\|_{L^\infty}) &\leq \mathbf{C}\|\mathbf{q}(0, \cdot)\|_{L^2}.\end{aligned}$$

Step 3

Let $q \in \mathbf{C}(\mathbb{R}, H^3(\mathbb{R}))$ is a solution of (NLS) such that $\|q(0, \cdot)\|_{L^2}$ is small.

- Let

$$\begin{aligned}\psi_1(t, x) &= c_1 e^{x/2} \varphi_1(t, x) + c_2 e^{-x/2} \chi_1(t, x), \\ \psi_2(t, x) &= c_1 e^{x/2} \varphi_2(t, x) + c_2 e^{-x/2} \chi_2(t, x).\end{aligned}$$

with $c_1 = ae^{(\gamma+i\theta)/2}$, $c_2 = ae^{-(\gamma+i\theta)/2}$, and $a \neq 0$.

- Let

$$Q(t, x) := -q(t, x) - \frac{2\psi_1(t, x)\overline{\psi_2(t, x)}}{|\psi_1(t, x)|^2 + |\psi_2(t, x)|^2}.$$

Then, $Q \in \mathbf{C}(\mathbb{R}, H^3(\mathbb{R}))$ is a solution of (NLS) and

$$\|Q(t, \cdot) - e^{i(t+\theta)} Q_1(\cdot + \gamma)\|_{L^2} \leq C \|q(0, \cdot)\|_{L^2} \quad \text{for } \forall t.$$

Step 4: Proof of L^2 -stability

Let $u_{n,0} \in H^3(\mathbb{R})$ be a sequence such that

$$\lim_{n \rightarrow \infty} \|u_{n,0} - u(0, \cdot)\|_{L^2} = 0.$$

Let $u_n(t, x)$ be a solution of (NLS) with $u_n(0, x) = u_{n,0}(x)$.

By the previous construction, there is an n -independent $C > 0$ such that

$$\sup_{t \in \mathbb{R}} \|u_n(t + t_n, \cdot + x_n) - Q_{k_n, v_n}\|_{L^2} + |k_n - 1| + |v_n| + |t_n| + |x_n| \leq C \|u_{n,0} - Q_1\|_{L^2}.$$

Therefore, there exists $k, v, t_0,$ and x_0 such that

$$k_n \rightarrow k, \quad v_n \rightarrow v, \quad x_n \rightarrow x_0, \quad t_n \rightarrow t_0 \quad \text{as } n \rightarrow \infty.$$

From L^2 -well-posedness, it then follows that

$$\sup_{t \in \mathbb{R}} \|u(t + t_0, \cdot + x_0) - Q_{k, v}\|_{L^2} + |k - 1| + |v| + |t_0| + |x_0| \leq C \|u(0, \cdot) - Q_1\|_{L^2}.$$

Discussion

Hayashi and Naumkin (1998) proved that if $\mathbf{q}_0 \in H^1(\mathbb{R}) \cap L^2_1(\mathbb{R})$ such that

$$\|\mathbf{q}_0\|_{H^1} + \|\langle \mathbf{x} \rangle \mathbf{q}_0\|_{L^2} \leq \epsilon \quad (\text{small}),$$

there exists a unique global solution in $H^1(\mathbb{R}) \cap L^2_1(\mathbb{R})$ such that

$$\|\mathbf{q}(\cdot, \mathbf{t})\|_{H^1} \leq \mathbf{C}\epsilon, \quad \|\mathbf{q}(\cdot, \mathbf{t})\|_{L^\infty} \leq \mathbf{C}\epsilon(1 + |\mathbf{t}|)^{-1/2}, \quad \mathbf{t} \in \mathbb{R}.$$

Note that $\|\langle \mathbf{x} \rangle \mathbf{q}(\cdot, \mathbf{t})\|_{L^2}$ and hence $\|\mathbf{q}(\cdot, \mathbf{t})\|_{L^1}$ may grow as $|\mathbf{t}| \rightarrow \infty$.

However, we are not able to prove that if $\|\mathbf{Q} - \mathbf{Q}_1\|_{H^1} \leq \|\mathbf{q}\|_{H^1}$ is small, then

$$\exists \mathbf{C} > 0 : \quad \|\mathbf{Q} - \mathbf{Q}_1\|_{L^\infty} \leq \mathbf{C}\|\mathbf{q}\|_{L^\infty},$$

without assuming that $\|\mathbf{q}\|_{L^1}$ is small.

Therefore, asymptotic stability of **1**-solitons in the cubic NLS equation is still an open problem.