

# Bäcklund transformation and $L^2$ -stability of NLS solitons

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# Introduction

Consider a 1D NLS equation,

$$iu_t = -u_{xx} + V(x)u - |u|^{2p}u, \quad \text{for } (t, x) \in \mathbb{R} \times \mathbb{R}.$$

where  $V : \mathbb{R} \rightarrow \mathbb{R}$  is a trapping potential and  $p > 0$  is the nonlinearity power.

Assume existence of solitons  $u(x, t) = \phi_\omega(x)e^{-i\omega t - i\theta}$  with some  $\omega \in \mathbb{R}$  and arbitrary  $\theta \in \mathbb{R}$ .

## Main questions:

- Orbital stability in  $H^1(\mathbb{R})$ : for any  $\epsilon > 0$  there is a  $\delta(\epsilon) > 0$ , such that if  $\|u(0) - \phi_\omega\|_{H^1} \leq \delta(\epsilon)$  then

$$\inf_{\theta \in \mathbb{R}} \|u(t) - e^{-i\theta} \phi_\omega\|_{H^1} \leq \epsilon, \quad \text{for all } t > 0.$$

- Asymptotic stability in  $L^\infty(\mathbb{R})$  (scattering to solitons): there is  $\omega_\infty$  near  $\omega$  such that

$$\liminf_{t \rightarrow \infty} \inf_{\theta \in \mathbb{R}} \|u(t) - e^{-i\theta} \phi_{\omega_\infty}\|_{L^\infty} = 0.$$

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# Previous literature

Orbital stability is well understood since the 1980s [Cazenave and Lions, 1982; Shatah and Strauss, 1985; Weinstein, 1986; Grillakis, Shatah and Strauss, 1987, 1990]. Regarding asymptotic stability,

- Buslaev and Sulem (2003) proved asymptotic stability of solitary waves in 1D NLS for the case  $p \geq 4$  using dispersive decay estimates from Buslaev and Perelman (1993).
- Cuccagna (2008) and Mizumachi (2008) improved the results with Strichartz analysis for the case  $p \geq 2$ .
- No results are available for  $p = 1$  even if  $V(x) \equiv 0$  (integrable case).

The difficulty comes from the slow decay of solutions in the  $L^\infty$  norm which makes it difficult to control convergence of modulation parameters.

# Scattering near zero

More results are available on asymptotic stability of zero solution for

$$iu_t + u_{xx} + |u|^{2p}u = 0.$$

- For  $p > 1$ , scattering near zero follows from the dispersive decay

$$\|e^{it\partial_x^2}\|_{L^1 \rightarrow L^\infty} \leq \frac{C}{t^{1/2}}, \quad t > 0.$$

because  $\|u(t, \cdot)\|_{L^\infty}^{2p}$  is absolutely integrable for  $p > 1$  (Ginibre & Velo, 1985; Ozawa, 1991; Cazenave & Weissler, 1992).

- Hayashi & Naumkin proved scattering for  $p = 1$  (1998) and  $p = 1/2$  (2008). In particular, for  $p = 1$ , they showed that if  $u_0 \in H^1(\mathbb{R})$  and  $xu \in L^2(\mathbb{R})$ , then

$$\|u(t, \cdot)\|_{H^1} \leq C\epsilon, \quad \|u(t, \cdot)\|_{L^\infty} \leq C\epsilon(1 + |t|)^{-1/2}, \quad t \in \mathbb{R}.$$

# Cubic NLS equation

We shall consider the cubic NLS equation,

$$iu_t + u_{xx} + 2|u|^2u = 0 \quad \text{for } (t, x) \in \mathbb{R} \times \mathbb{R}. \quad (\text{NLS})$$

- (NLS) is an integrable Hamiltonian system and has infinitely many conservation laws (Zakharov and Shabat, 1972):

$$N := \|u(t, \cdot)\|_{L^2}, \quad E := \frac{1}{2} \int_{\mathbb{R}} (|u_x(t, x)|^2 - |u(t, x)|^4) dx$$

- (NLS) is locally well-posed in  $L^2$  (Tsutsumi, 1987). Thanks to  $L^2$  conservation, it is globally well-posed in  $L^2$ .
- (NLS) is also well-posed in  $H^k$  for any  $k \in \mathbb{N}$  (Ginibre & Velo, 1984; Kato, 1987).

# Soliton solutions

- (NLS) has a 4-parameter family of 1-solitons

$$Q_{k,v}(t + t_0, x + x_0) = Q_k(x - vt) e^{ivx/2 + i(k^2 - v^2/4)t},$$

where

$$Q_k(x) = k \operatorname{sech}(kx), \quad k > 0, \quad v \in \mathbb{R}, \quad x_0 \in \mathbb{R}, \quad t_0 \in \mathbb{R}.$$

- $Q_k$  is a minimizer of  $E|_{\mathcal{M}}$ , where

$$\mathcal{M} = \{u \in H^1(\mathbb{R}), \|u\|_{L^2} = \|Q_k\|_{L^2}\},$$

hence, it is orbitally stable (Cazenave and Lions, 1982).

- Perturbations near solitons in  $H^s$  for  $0 < s < 1$  may grow at most polynomially in time (Colliander-Keel-Staffilani-Takaoka-Tao, 2003).

# Soliton solutions

## Main Questions:

- Is **1**-soliton orbitally stable in  $L^2$ ?
- Is **1**-soliton asymptotically stable in  $H^1$  or  $L^2$ ?

We aim to show the Lyapunov stability of **1**-solitons in  $L^2$ .

We use the Bäcklund transformation to define an isomorphism which maps solutions in an  $L^2$ -neighborhood of the zero solution to those in an  $L^2$ -neighborhood of a **1**-soliton.

A Bäcklund transformation is a mapping between two solutions of the same (or different) equations. It was originally found for the sine-Gordon equation by Bianchi (1879) and Bäcklund (1882) but was extended to KdV, KP, Benjamin-Ono, Toda, and other integrable equations in 1970s.



# Bäcklund transformation of (NLS)

For (NLS), consider the Lax operator system,

$$\partial_x \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} = \begin{pmatrix} \eta & \mathbf{q} \\ -\bar{\mathbf{q}} & -\eta \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix}, \quad (\text{Lax1})$$

$$\partial_t \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} = \begin{pmatrix} 2\eta^2 + |\mathbf{q}|^2 & \partial_x \mathbf{q} + 2\eta \mathbf{q} \\ \partial_x \bar{\mathbf{q}} - 2\eta \bar{\mathbf{q}} & -2\eta^2 - |\mathbf{q}|^2 \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix}, \quad (\text{Lax2})$$

where  $\eta$  is the spectral parameter.

(Lax1) and (Lax2) are compatible if  $i\mathbf{q}_t + \mathbf{q}_{xx} + 2|\mathbf{q}|^2\mathbf{q} = \mathbf{0}$ .

Let  $\mathbf{q}(\mathbf{t}, \mathbf{x})$  be a solution of (NLS) and  $(\psi_1, \psi_2)$  be a solution of (Lax1)–(Lax2) for  $\eta \in \mathbb{R}$ . Define

$$\mathbf{Q} := -\mathbf{q} - \frac{4\eta\psi_1\bar{\psi}_2}{|\psi_1|^2 + |\psi_2|^2}.$$

Then  $\mathbf{Q}(\mathbf{t}, \mathbf{x})$  is a solution of (NLS). (Chen'74, Konno and Wadati '75)

Bäcklund transformation  $\mathbf{0} \rightarrow \mathbf{1}$  soliton

- Let  $\eta = \frac{1}{2}$  and  $\mathbf{q} \equiv \mathbf{0}$ . Then,

$$\psi_1 = e^{(x+it)/2}, \quad \psi_2 = -e^{-(x+it)/2} \Rightarrow \mathbf{Q} = e^{it} \operatorname{sech}(x).$$

- Let  $\Psi_1 = \frac{\bar{\psi}_2}{|\psi_1|^2 + |\psi_2|^2}$  and  $\Psi_2 = \frac{\psi_1}{|\psi_1|^2 + |\psi_2|^2}$ . Then  $(\Psi_1, \Psi_2)$  satisfy the Lax operator system:

$$\partial_x \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix} = \begin{pmatrix} \eta & \mathbf{Q} \\ -\bar{\mathbf{Q}} & -\eta \end{pmatrix} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix}, \quad (\text{Lax}'1)$$

$$\partial_t \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix} = \begin{pmatrix} 2\eta^2 + |\mathbf{Q}|^2 & \partial_x \mathbf{Q} + 2\eta \mathbf{Q} \\ \partial_x \bar{\mathbf{Q}} - 2\eta \bar{\mathbf{Q}} & -2\eta^2 - |\mathbf{Q}|^2 \end{pmatrix} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix}. \quad (\text{Lax}'2)$$

- If  $\mathbf{Q} = e^{it} \operatorname{sech}(x)$ , then  $\eta = \frac{1}{2}$  is an eigenvalue of (Lax'1) with

$$\Psi_1 = -e^{(-x+it)/2} \operatorname{sech}(x), \quad \Psi_2 = e^{(x+it)/2} \operatorname{sech}(x).$$

# Applications of Bäcklund transformation

We show Lyapunov stability of **1**-solitons in the  $L^2$  class.

$$\begin{array}{ccc}
 \mathbf{Q}(\mathbf{0}, \mathbf{x}) & \xrightarrow{NLS} & \mathbf{Q}(\mathbf{t}, \mathbf{x}) & \|\mathbf{Q}(\mathbf{0}, \cdot) - \mathbf{Q}_1\|_{L^2} \text{ is small,} \\
 \downarrow BT & & \uparrow BT & \\
 \mathbf{q}_0(\mathbf{x}) & \xrightarrow{NLS} & \mathbf{q}(\mathbf{t}, \mathbf{x}) & \|\mathbf{q}(\mathbf{t})\|_{L^2} = \|\mathbf{q}(\mathbf{0})\|_{L^2} \text{ is small.}
 \end{array}$$

- Merle and Vega (2003) used the Miura transformation to prove asymptotic stability of KdV solitons in  $L^2$ .
- Mizumachi and Tzvetkov (2011) applied the same transformation to prove  $L^2$ -stability of line solitons in the KP-II equation under periodic transverse perturbations.
- Mizumachi and Pego (2008) used Backlund transformation to prove asymptotic stability of Toda lattice solitons.
- Hoffman and Wayne (2009) extended this result to two and  $N$  Toda lattice solitons.

# Main result

## Theorem

(Mizumachi, P., 2012) Fix  $\mathbf{k}_0 > \mathbf{0}$ . Let  $\mathbf{u}(\mathbf{t}, \mathbf{x})$  be a solution of (NLS) in the class

$$\mathbf{u} \in \mathbf{C}(\mathbb{R}; L^2(\mathbb{R})) \cap L^8_{loc}(\mathbb{R}; L^4(\mathbb{R})).$$

There exist  $\mathbf{C}, \varepsilon > \mathbf{0}$  such that if  $\|\mathbf{u}(\mathbf{0}, \cdot) - \mathbf{Q}_{\mathbf{k}_0}\|_{L^2} < \varepsilon$ , then there exist  $\mathbf{k}, \mathbf{v}, \mathbf{t}_0, \mathbf{x}_0$  such that

$$\sup_{\mathbf{t} \in \mathbb{R}} \|\mathbf{u}(\mathbf{t} + \mathbf{t}_0, \cdot + \mathbf{x}_0) - \mathbf{Q}_{\mathbf{k}, \mathbf{v}}\|_{L^2} + |\mathbf{k} - \mathbf{k}_0| + |\mathbf{v}| + |\mathbf{t}_0| + |\mathbf{x}_0| \leq \mathbf{C} \|\mathbf{u}(\mathbf{0}, \cdot) - \mathbf{Q}_{\mathbf{k}_0}\|_{L^2}.$$

**Remark:** In KdV, perturbations of **1**-solitons can cause logarithmic growth of the phase shift due to collisions with small solitary waves (Martel and Merle, 2005). For the cubic NLS, a solution remains in the neighborhood of a **1**-soliton for all the time.

# Outline of the proof

For the sake of simplicity, we consider  $\mathbf{k}_0 = \mathbf{1}$  ( $\eta = \frac{1}{2}$ ).

$$\begin{array}{ccc}
 \mathbf{Q}(\mathbf{0}, \mathbf{x}) & \xrightarrow{NLS} & \mathbf{Q}(\mathbf{t}, \mathbf{x}) \\
 \downarrow BT & & \uparrow BT \\
 \mathbf{q}_0(\mathbf{x}) & \xrightarrow{NLS} & \mathbf{q}(\mathbf{t}, \mathbf{x})
 \end{array}
 \quad
 \begin{array}{l}
 \|\mathbf{Q}(\mathbf{0}, \cdot) - \mathbf{Q}_1\|_{L^2} \text{ is small,} \\
 \|\mathbf{q}(\mathbf{t})\|_{L^2} = \|\mathbf{q}(\mathbf{0})\|_{L^2} \text{ is small.}
 \end{array}$$

- Step 1: From a nearly  $\mathbf{1}$ -soliton to a nearly zero solution at  $\mathbf{t} = \mathbf{0}$ .
- Step 2: Time evolution of the nearly zero solution for  $\mathbf{t} \in \mathbb{R}$ .
- Step 3: From the nearly zero solution to the nearly  $\mathbf{1}$ -soliton for  $\mathbf{t} \in \mathbb{R}$ .
- Step 4: Approximation arguments in  $\mathbf{H}^3(\mathbb{R})$  to control modulations of parameters of  $\mathbf{1}$ -solitons for all  $\mathbf{t} \in \mathbb{R}$ .

# Step 1: From 1-soliton to 0-soliton at $t = 0$ .

At  $t = 0$ ,  $\mathbf{Q}$  is close to  $\mathbf{Q}_1 = \operatorname{sech}(x)$  and  $\eta$  is close to  $\frac{1}{2}$ .

If  $\mathbf{Q} = \mathbf{Q}_1$  and  $\eta = \frac{1}{2}$ , then the Lax operator

$$\partial_x \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix} = \begin{pmatrix} \eta & \mathbf{Q} \\ -\bar{\mathbf{Q}} & -\eta \end{pmatrix} \begin{pmatrix} \Psi_1 \\ \Psi_2 \end{pmatrix},$$

has two linearly independent solutions

$$\begin{bmatrix} -e^{-x/2} \\ e^{x/2} \end{bmatrix} \operatorname{sech}(x), \quad \begin{bmatrix} (e^x + 2(1+x)e^{-x})e^{x/2} \\ (e^{-x} - 2xe^x)e^{-x/2} \end{bmatrix} \operatorname{sech}(x).$$

Define

$$\mathbf{q} := -\mathbf{Q}_1 - \frac{4\eta\Psi_1\bar{\Psi}_2}{|\Psi_1|^2 + |\Psi_2|^2}.$$

Then  $\mathbf{q} = \mathbf{0}$  follows from the first (decaying) solution and

$$\mathbf{q}(x) = \frac{2xe^{2x} + (4x^2 + 4x - 1) - 2x(1+x)e^{-2x}}{\cosh(3x) + 4(1+x+x^2)\cosh(x)} - \operatorname{sech}(x)$$

follows from the second (growing) solution.

# Step 1

By perturbation theory (Lyapunov–Schmidt reduction method), we prove:

- If  $\|\mathbf{Q} - \mathbf{Q}_1\|_{L^2}$  is small, then there exists  $\eta = (\mathbf{k} + i\nu)/2$  and  $\Psi \in H^1(\mathbb{R})$  such that

$$|\mathbf{k} - 1| + |\nu| + \|\Psi - \Psi_1\|_{H^1} \leq C\|\mathbf{Q} - \mathbf{Q}_1\|_{L^2}.$$

- If

$$\mathbf{q} := -\mathbf{Q} - \frac{2k\Psi_1\bar{\Psi}_2}{|\Psi_1|^2 + |\Psi_2|^2},$$

then  $\mathbf{q} \in L^2(\mathbb{R})$  and

$$\begin{aligned} \|\mathbf{q}_0\|_{L^2} &\leq \|\mathbf{Q} - \mathbf{Q}_1\|_{L^2} + \left\| \mathbf{Q}_1 + \frac{2k\Psi_1\bar{\Psi}_2}{|\Psi_1|^2 + |\Psi_2|^2} \right\|_{L^2} \\ &\lesssim \|\mathbf{Q} - \mathbf{Q}_1\|_{L^2}. \end{aligned}$$

- Moreover, if  $\mathbf{Q} \in H^3(\mathbb{R})$ , then  $\mathbf{q} \in H^3(\mathbb{R})$ .

## Step 2: Time evolution near $\mathbf{0}$ -soliton for $\mathbf{t} \in \mathbb{R}$ .

If  $\mathbf{q}(\mathbf{0}, \cdot) \in \mathbf{H}^3(\mathbb{R})$  and  $\|\mathbf{q}(\mathbf{0}, \cdot)\|_{L^2}$  is small, then  $\mathbf{q} \in \mathbf{C}(\mathbb{R}, \mathbf{H}^3(\mathbb{R}))$  and

$$\|\mathbf{q}(\mathbf{t}, \cdot)\|_{L^2} = \|\mathbf{q}(\mathbf{0}, \cdot)\|_{L^2}$$

remains small for all  $\mathbf{t} \in \mathbb{R}$ .

This result completes step 2 for the NLS equation.



# Step 3: From 0-soliton to 1-soliton for $t \in \mathbb{R}$ .

If  $\mathbf{q} \equiv \mathbf{0}$ , then  $\{(\mathbf{e}^{x/2}, \mathbf{0}), (\mathbf{0}, \mathbf{e}^{-x/2})\}$  is a fundamental system of (Lax1).

If  $\mathbf{q} = \mathbf{q}(\mathbf{0}, \mathbf{x})$  is small in  $L^2$ , there exist bounded solutions of (Lax1):

$$\mathbf{e}^{x/2} \vec{\varphi}(\mathbf{x}) = \mathbf{e}^{x/2}(\varphi_1(\mathbf{x}), \varphi_2(\mathbf{x})), \quad \mathbf{e}^{-x/2} \vec{\chi}(\mathbf{x}) = \mathbf{e}^{-x/2}(\chi_1(\mathbf{x}), \chi_2(\mathbf{x})),$$

where

$$\begin{cases} \varphi_1' = \mathbf{q}\varphi_2, \\ \varphi_2' = -\bar{\mathbf{q}}\varphi_1 - \varphi_2, \end{cases}, \quad \begin{cases} \chi_1' = \chi_1 + \mathbf{q}\chi_2, \\ \chi_2' = -\bar{\mathbf{q}}\chi_1, \end{cases}$$

$$\lim_{x \rightarrow \infty} \varphi_1(\mathbf{x}) = 1, \quad \lim_{x \rightarrow -\infty} \chi_2(\mathbf{x}) = -1.$$

A bounded solution  $(\varphi_1, \varphi_2)$  satisfies

$$\begin{cases} \varphi_1(\mathbf{x}) = 1 - \int_x^\infty \mathbf{q}(\mathbf{y})\varphi_2(\mathbf{y})d\mathbf{y} =: T_1(\varphi_1, \varphi_2)(\mathbf{x}), \\ \varphi_2(\mathbf{x}) = - \int_{-\infty}^x \mathbf{e}^{-(\mathbf{x}-\mathbf{y})} \bar{\mathbf{q}}(\mathbf{y})\varphi_1(\mathbf{y})d\mathbf{y} =: T_2(\varphi_1, \varphi_2)(\mathbf{x}). \end{cases}$$

## Step 3

- Note that we are not using here any smallness of  $\|\mathbf{q}\|_{L^1}$ , a typical assumption in inverse scattering to guarantee no solitons in  $\mathbf{q}(t, \mathbf{x})$ .
- If  $\|\mathbf{q}\|_{L^2}$  is small, then  $\mathcal{T} = (\mathcal{T}_1, \mathcal{T}_2)$  is a contraction mapping on  $L^\infty \times (L^\infty \cap L^2)$  and

$$\begin{aligned} \|\varphi_1 - \mathbf{1}\|_{L^\infty} + \|\varphi_2\|_{L^\infty \cap L^2} &\leq \mathbf{C}\|\mathbf{q}\|_{L^2}, \\ \|\chi_1\|_{L^\infty \cap L^2} + \|\chi_2 + \mathbf{1}\|_{L^\infty} &\leq \mathbf{C}\|\mathbf{q}\|_{L^2}. \end{aligned}$$

- If  $\mathbf{q}(t, \mathbf{x})$  is an  $H^3(\mathbb{R})$ -solution of (NLS), then

$$\begin{aligned} \sup_t (\|\varphi_1(t, \cdot) - e^{it/2}\|_{L^\infty} + \|\varphi_2(t, \cdot)\|_{L^2 \cap L^\infty}) &\leq \mathbf{C}\|\mathbf{q}(0, \cdot)\|_{L^2}, \\ \sup_t (\|\chi_1(t, \cdot)\|_{L^2 \cap L^\infty} + \|\chi_2(t, \cdot) + e^{-it/2}\|_{L^\infty}) &\leq \mathbf{C}\|\mathbf{q}(0, \cdot)\|_{L^2}. \end{aligned}$$

## Step 3

Let  $\mathbf{q} \in \mathbf{C}(\mathbb{R}, \mathbf{H}^3(\mathbb{R}))$  is a solution of (NLS) such that  $\|\mathbf{q}(\mathbf{0}, \cdot)\|_{L^2}$  is small.

- Let

$$\begin{aligned}\psi_1(t, \mathbf{x}) &= \mathbf{c}_1 e^{x/2} \varphi_1(t, \mathbf{x}) + \mathbf{c}_2 e^{-x/2} \chi_1(t, \mathbf{x}), \\ \psi_2(t, \mathbf{x}) &= \mathbf{c}_1 e^{x/2} \varphi_2(t, \mathbf{x}) + \mathbf{c}_2 e^{-x/2} \chi_2(t, \mathbf{x}).\end{aligned}$$

with  $\mathbf{c}_1 = \mathbf{a}e^{(\gamma+i\theta)/2}$ ,  $\mathbf{c}_2 = \mathbf{a}e^{-(\gamma+i\theta)/2}$ , and  $\mathbf{a} \neq \mathbf{0}$ .

- Let

$$\mathbf{Q}(t, \mathbf{x}) := -\mathbf{q}(t, \mathbf{x}) - \frac{2\psi_1(t, \mathbf{x})\overline{\psi_2(t, \mathbf{x})}}{|\psi_1(t, \mathbf{x})|^2 + |\psi_2(t, \mathbf{x})|^2}.$$

Then,  $\mathbf{Q} \in \mathbf{C}(\mathbb{R}, \mathbf{H}^3(\mathbb{R}))$  is a solution of (NLS) and

$$\|\mathbf{Q}(t, \cdot) - e^{i(t+\theta)} \mathbf{Q}_1(\cdot + \gamma)\|_{L^2} \leq \mathbf{C} \|\mathbf{q}(\mathbf{0}, \cdot)\|_{L^2} \quad \text{for } \forall t.$$

# Step 4: Proof of $L^2$ -stability

Let  $u_{n,0} \in H^3(\mathbb{R})$  be a sequence such that

$$\lim_{n \rightarrow \infty} \|u_{n,0} - u(0, \cdot)\|_{L^2} = 0.$$

Let  $u_n(t, x)$  be a solution of (NLS) with  $u_n(0, x) = u_{n,0}(x)$ .

By the previous construction, there is an  $n$ -independent  $C > 0$  such that

$$\sup_{t \in \mathbb{R}} \|u_n(t + t_n, \cdot + x_n) - Q_{k_n, v_n}\|_{L^2} + |k_n - 1| + |v_n| + |t_n| + |x_n| \leq C \|u_{n,0} - Q_1\|_{L^2}.$$

Therefore, there exists  $k, v, t_0$ , and  $x_0$  such that

$$k_n \rightarrow k, \quad v_n \rightarrow v, \quad x_n \rightarrow x_0, \quad t_n \rightarrow t_0 \quad \text{as } n \rightarrow \infty.$$

From  $L^2$ -well-posedness, it then follows that

$$\sup_{t \in \mathbb{R}} \|u(t + t_0, \cdot + x_0) - Q_{k, v}\|_{L^2} + |k - 1| + |v| + |t_0| + |x_0| \leq C \|u(0, \cdot) - Q_1\|_{L^2}.$$

# Discussion: asymptotic stability

Hayashi and Naumkin (1998) proved that if  $\mathbf{q}_0 \in H^1(\mathbb{R}) \cap L^1(\mathbb{R})$  such that

$$\|\mathbf{q}_0\|_{H^1} + \|\mathbf{q}_0\|_{L^1} \leq \epsilon \quad (\text{small}),$$

there exists a unique global solution in  $H^1(\mathbb{R})$  such that

$$\|\mathbf{q}(\cdot, t)\|_{H^1} \leq C\epsilon, \quad \|\mathbf{q}(\cdot, t)\|_{L^\infty} \leq C\epsilon(1 + |t|)^{-1/2}, \quad t \in \mathbb{R}.$$

Note that  $\|\mathbf{q}(\cdot, t)\|_{L^1}$  may grow as  $|t| \rightarrow \infty$ .

However, we are not able to prove that if  $\|\mathbf{Q} - \mathbf{Q}_1\|_{H^1} \leq \|\mathbf{q}\|_{H^1}$  is small, then

$$\exists C > 0 : \quad \|\mathbf{Q} - \mathbf{Q}_1\|_{L^\infty} \leq C\|\mathbf{q}\|_{L^\infty},$$

without assuming that  $\|\mathbf{q}\|_{L^1}$  is small.

Asymptotic stability of **1**-solitons in (NLS) is still an open problem.

# Discussion: Hasimoto transformation

The integrable Landau–Lifshitz (LL) model is

$$\mathbf{u}_t = \mathbf{u} \times \mathbf{u}_{xx}, \quad (\text{LL})$$

where  $\mathbf{u}(t, \mathbf{x}) : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{S}^2$  such that  $\mathbf{u} \cdot \mathbf{u} = \mathbf{1}$ . NLS and LL equations are connected by the Hasimoto (Miura-type) transformation.

- $L^2$ -orbital stability of  $\mathbf{1}$ -solitons of (NLS) is related to  $H^1$ -orbital stability of the domain wall solutions of (MTM).
- $H^1$ -asymptotic stability of  $\mathbf{1}$ -solitons of (NLS) is related to  $H^2$ -asymptotic stability of domain wall solutions of (MTM)

# Discussion: nonlinear Dirac equation

The nonlinear Dirac equations (the massive Thirring model) is

$$\begin{cases} i(\mathbf{u}_t + \mathbf{u}_x) + \mathbf{v} = 2|\mathbf{v}|^2\mathbf{u}, \\ i(\mathbf{v}_t - \mathbf{v}_x) + \mathbf{u} = 2|\mathbf{u}|^2\mathbf{v}, \end{cases} \quad (\text{MTM})$$

where  $(\mathbf{u}, \mathbf{v}) : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{C}^2$ .

Orbital stability of **0**-solution or **1**-solitons is a difficult problem because the energy functional is sign-indefinite. Asymptotic stability approaches (if they work) give the orbital stability.

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