

Dynamics of shocks in the modular Burgers equation

Dmitry Pelinovsky

Department of Mathematics, McMaster University

with

Uyen Le - McMaster University

Pascal Poulet - Universite de Antilles

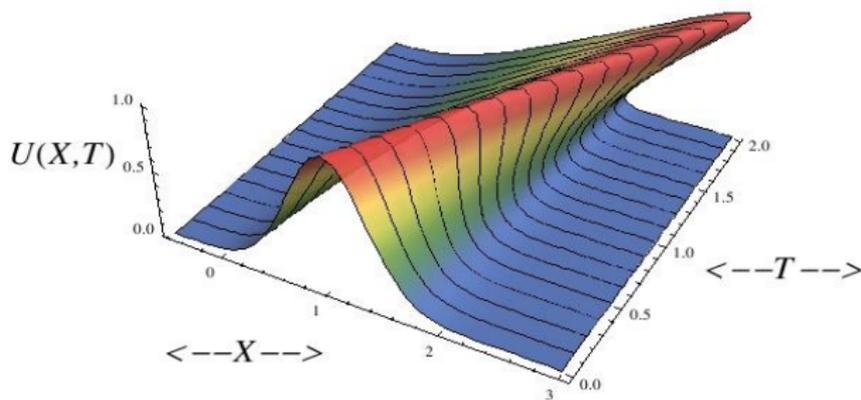
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Inviscid Shocks

- Dynamics of a Conservation Law

$$\partial_t v + \partial_x f(v) = 0$$

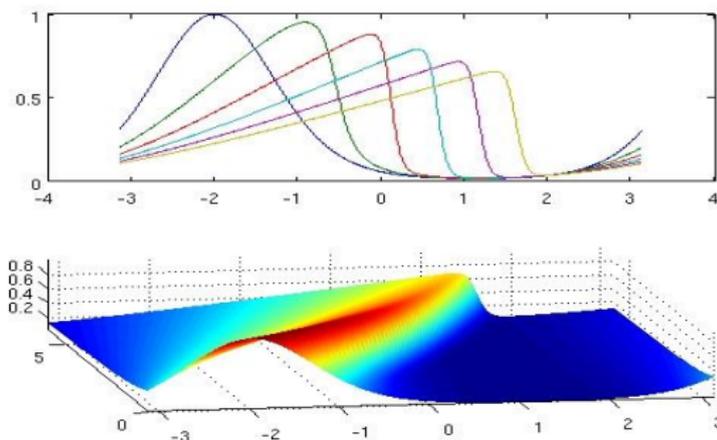
generate shock singularities in finite time from a large class of smooth data and for smooth $f(v)$.



Viscous Shocks

- Diffusive regularization leads to a viscous Burgers equation

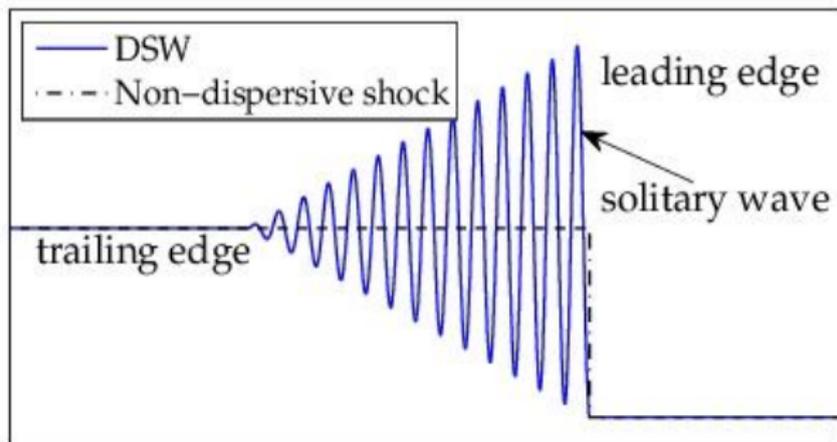
$$\partial_t v + \partial_x f(v) = \varepsilon^2 \partial_x^2 v.$$



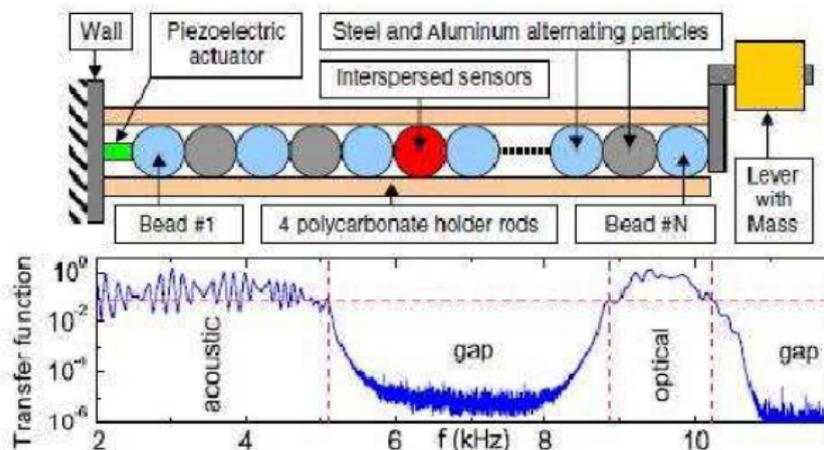
Dispersive Shocks

- Dispersive regularization leads to the Korteweg–de Vries equation

$$\partial_t v + \partial_x f(v) + \varepsilon^3 \partial_x^3 v = 0.$$



Granular chains



- Granular chains contain densely packed, elastically interacting particles with Hertzian contact forces.
- N. Boechler, G. Theocharis, P.G. Kevrekidis, M.A. Porter, C. Daraio.

Logarithmic models

Granular chains are modeled with Newton's equations of motion:

$$x_n''(t) = V'(x_{n+1} - x_n) - V'(x_n - x_{n-1}), \quad n \in \mathbb{Z},$$

where x_n is the displacement of the n th particle and V is the interaction potential for spherical beads (H. Hertz, 1882):

$$V(x) = |x|^{1+\alpha} H(-x), \quad \alpha = \frac{3}{2},$$

where H is the step (Heaviside) function. For hollow materials, $\alpha \rightarrow 1$.

- The conservative model yields the logarithmic KdV equation

$$\partial_t v + \partial_x(v \log |v|) + \partial_x^3 v = 0$$

- The dissipative model yields the logarithmic Burgers equation

$$\partial_t v + \partial_x(v \log |v|) = \partial_x^2 v$$

G. James & D. P., 2014; G. James, 2021

Modular nonlinearity

In a similar context of dynamics of particles with piecewise interaction potentials, models with modular nonlinearities have been derived:

- The modular KdV equation

$$\partial_t v + \partial_x |v| + \partial_x^3 v = 0$$

- The modular Burgers equation

$$\partial_t v = \partial_x |v| + \partial_x^2 v$$

C. M. Hedberg, O. V. Rudenko, 2016–2018

The models are linear for sign-definite solutions. Nonlinear waves correspond to the sign-changing solutions, for which the modeling problem becomes a moving interface problem between solutions of linear equations.

Traveling waves in the modular Burgers equation

Starting with

$$\partial_t v = \partial_x |v| + \partial_x^2 v,$$

we can think of the traveling wave solutions $v(t, x) = W(x - ct)$, where

$$W''(x) + \text{sign}(W)W'(x) + cW'(x) = 0, \quad x \in \mathbb{R}.$$

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Q What is the function space for solutions?

A Space of piecewise C^2 functions satisfying the interface condition

$$[W''']_-(x_0) = -2|W'(x_0)|$$

at each interface located at x_0 , where $[f]_-(x_0) = f(x_0^+) - f(x_0^-)$ is the jump of a piecewise continuous function f across x_0 .

Traveling waves in the modular Burgers equation

Integrating once yields

$$W'(x) + |W(x)| + cW(x) = d, \quad x \in \mathbb{R},$$

where the constant of integration is identical for all pieces of piecewise C^2 function $W(x) : \mathbb{R} \rightarrow \mathbb{R}$.

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If $W_{\pm} = \lim_{x \rightarrow \pm\infty} W(x)$, then bounded solutions only exist if $W_- < 0 < W_+$ with uniquely selected speed

$$c = \frac{W_+ + W_-}{W_+ - W_-}$$

and uniquely defined profile W up to spatial translations:

$$W(x) = \begin{cases} W_+(1 - e^{-(1+c)x}), & x > 0, \\ W_-(1 - e^{(1-c)x}), & x < 0. \end{cases}$$

If $W_+ = -W_-$, then $c = 0$ and $W(-x) = -W(x)$ is odd.

Motivational questions

- 1 Is the viscous shock W stable in the time evolution of the modular Burgers equation?
- 2 How does the interface moves in the time evolution depending on the initial conditions?
- 3 Is there the finite-time extinction of the area between two consequent interfaces?
- 4 How can we model the moving interface problems numerically?

Interface equation

It is natural to look for solutions of the modular Burgers equation

$$\partial_t v = \partial_x |v| + \partial_x^2 v$$

in class of piecewise C^2 functions.

If $v(t, \xi(t)) = 0$ defines the interface at $x = \xi(t)$, then

$$[v_t]_-^+(\xi(t)) = 0 \quad \text{and} \quad [v_x]_-^+(\xi(t)) = 0,$$

whereas

$$[v_{xx}]_-^+(\xi(t)) = -2|v_x(t, \xi(t))|$$

determines the interface equation for $\xi(t)$, $t > 0$.

Simple case: odd data

It follows from

$$\partial_t v = \partial_x |v| + \partial_x^2 v$$

that if $v(0, -x) = -v(0, x)$ is odd at $t = 0$, then $v(t, -x) = -v(t, x)$ remains odd for all $t > 0$. The interface is located at $\xi(t) = 0$, $t > 0$.

Adding an odd perturbation $w(t, x)$ to the odd viscous shock $W(x) = (1 - e^{-|x|})\text{sgn}(x)$ with $c = 0$ as $v(t, x) = W(x) + w(t, x)$, we get the linear initial-boundary-value problem

$$\begin{cases} w_t = w_x + w_{xx}, & x > 0, & t > 0, \\ w(t, 0) = 0, & & t > 0, \\ w(t, x) \rightarrow 0 & \text{as } x \rightarrow +\infty, & t > 0, \\ w(0, x) = w_0(x), & x > 0, & \end{cases}$$

Main result: odd data

Theorem (Le, Pelinovsky, Pouillet, 2021)

For every $\epsilon > 0$ there is $\delta > 0$ such that for every odd v_0 satisfying

$$\|v_0 - W\|_{H^2} < \delta,$$

there exists a unique odd solution $v(t, x)$ with $v(0, x) = v_0(x)$ satisfying

$$\|v(t, \cdot) - W\|_{H^2} < \epsilon, \quad t > 0$$

and

$$\|v(t, \cdot) - W\|_{W^{2,\infty}} \rightarrow 0 \quad \text{as} \quad t \rightarrow +\infty.$$

- Since $W(0) = 0$, $W'(0) = 1$, and H^2 is embedded into C^1 , we have $v(t, x) = W(x) + w(t, x) > 0$ for every $x > 0$ and $t > 0$.
- The result is extended to $W(x - ct)$ under suitably scaled data.

General case: single interface

Consider the viscous shock $W(x) = (1 - e^{-|x|})\text{sgn}(x)$ with $c = 0$ but make no assumption on the symmetry of the perturbations. With the decomposition

$$v(t, x) = W(x - \xi(t)) + w(t, x - \xi(t)), \quad y = x - \xi(t),$$

we have now the linear initial-boundary-value problem

$$\begin{cases} w_t = (\xi'(t) \pm 1)w_y + w_{yy} + \xi'(t)W'(y), & \pm y > 0, & t > 0, \\ w(t, 0) = 0, & & t > 0, \\ w(t, x) \rightarrow 0 & \text{as } y \rightarrow \pm\infty, & t > 0, \\ w(0, y) = w_0(y), & y \in \mathbb{R}, & \end{cases}$$

The two equations on half-lines are coupled by the interface conditions

$$(\xi'(t) \pm 1)w_y(t, 0^\pm) + w_{yy}(t, 0^\pm) + \xi'(t) = 0,$$

which are consistent due to the conditions $[u_{xx}]_-(\xi(t)) = -2|u_x(t, \xi(t))|$.

Main result: general data

Theorem (Le, Pelinovsky, Pouillet, 2021)

Fix $\alpha \in (0, \frac{1}{2})$. For every $\epsilon > 0$ there is $\delta > 0$ s.t. for every v_0 s.t.

$$\|v_0 - W\|_{H^2 \cap W^{2,\infty}} + \|e^{\alpha|\cdot|}(v_0 - W)\|_{W^{2,\infty}} < \delta$$

there exists a unique solution $v(t, x)$ with $v(0, x) = v_0(x)$ satisfying

$$\|v(t, \cdot + \xi(t)) - W\|_{H^2 \cap W^{2,\infty}} < \epsilon, \quad t > 0$$

and

$$\|v(t, \cdot + \xi(t)) - W\|_{W^{2,\infty}} \rightarrow 0 \quad \text{as } t \rightarrow +\infty,$$

with $\xi' \in L^1(\mathbb{R}_+) \cap L^\infty(\mathbb{R}_+)$ and $\xi_\infty := \lim_{t \rightarrow +\infty} \xi(t)$.

Reformulation for numerical approximations

The original problem for general perturbation $w(t, y)$ with $y = x - \xi(t)$:

$$\begin{cases} w_t = (\xi'(t) \pm 1)w_y + w_{yy} + \xi'(t)e^{-y}, & \pm y > 0, & t > 0, \\ w(t, 0) = 0, & & t > 0, \\ w(t, x) \rightarrow 0 & \text{as } y \rightarrow \pm\infty, & t > 0, \\ w(0, y) = w_0(y), & y \in \mathbb{R}, & \end{cases}$$

By using variables $v^\pm(t, y) := w(t, y) \mp w(t, -y)$ with $y > 0$ we obtain the coupled system

$$\begin{cases} v_t^+ = v_y^+ + v_{yy}^+ + \xi'(t)v_y^-, & y > 0, \\ v_t^- = v_y^- + v_{yy}^- + \xi'(t)v_y^+ + 2\xi'(t)e^{-y}, & y > 0, \end{cases}$$

subject to $v^\pm(t, 0) = 0$, $v_y^-(t, 0) = 0$, and $\xi'(t) = -\frac{v_{yy}^-(t, 0)}{2+v_y^+(t, 0)}$.

Remarks on the numerical method

- Central-difference approximation of spatial derivatives.
- Neumann condition for $v_y^-(t, 0) = 0$ is modelled with an extra grid point $v_{-1}^-(t) = v_1^-(t)$.
- The smoothness condition for $v_y^+(t, 0) + v_{yy}^+(t, 0) = 0$ is modelled with an extra grid point

$$v_{-1}^+(t) = -\frac{2+h}{2-h}v_1^+(t).$$

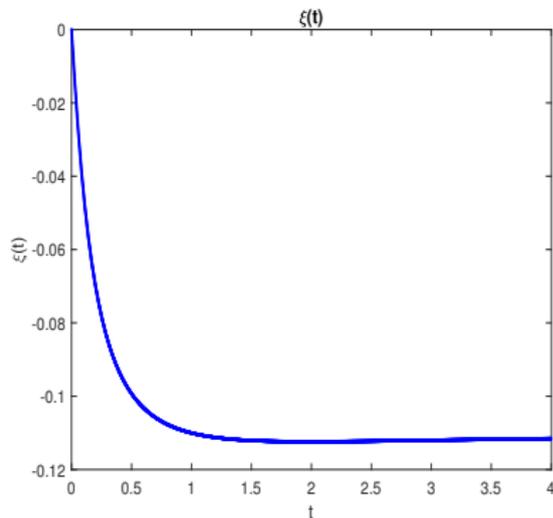
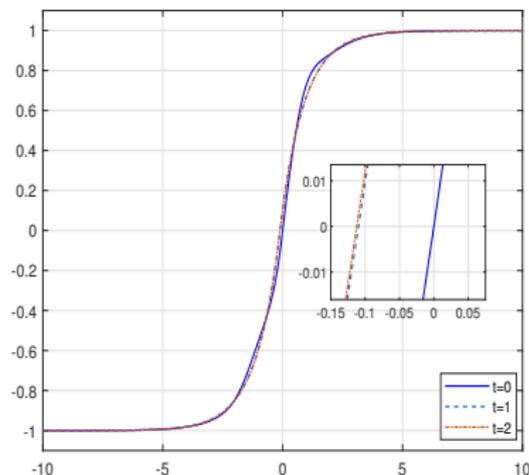
- The interface condition $\xi'(t) = -\frac{v_{yy}^-(t, 0)}{2+v_y^+(t, 0)}$ is resolved as

$$\xi'(t) = -\frac{(2-h)v_1^-(t)}{hv_1^+(t) + h^2(2-h)}.$$

- Time steps are performed with the implicit Crank-Nicholson method

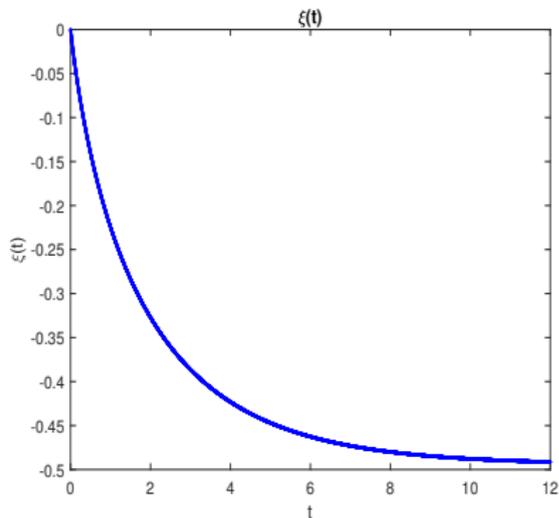
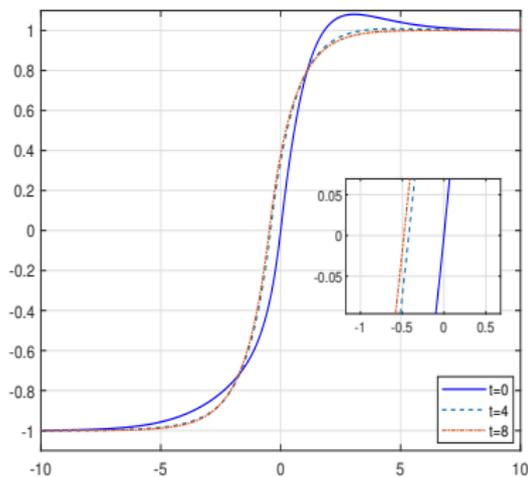
Initial data with Gaussian decay

$$v^+(0, y) = 0.1(y - 0.5y^2)e^{-y^2}, \quad v^-(0, y) = 0.5y^2e^{-y^2}.$$

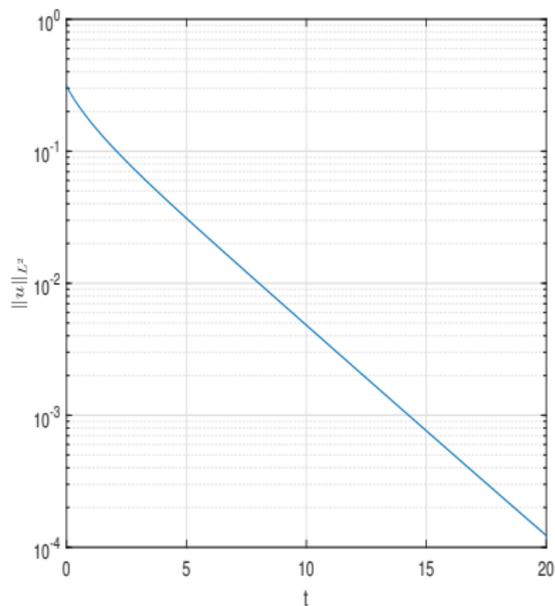
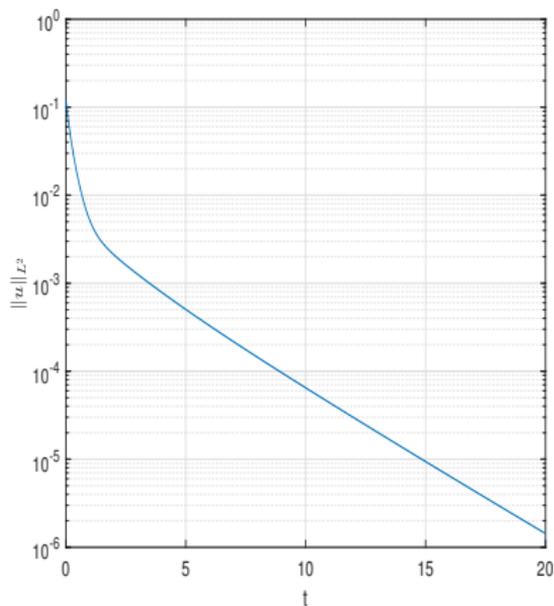


Initial data with exponential decay

$$v^+(0, y) = 0.1(y + 0.5y^2)e^{-y}, \quad v^-(0, y) = 0.5y^2e^{-y},$$

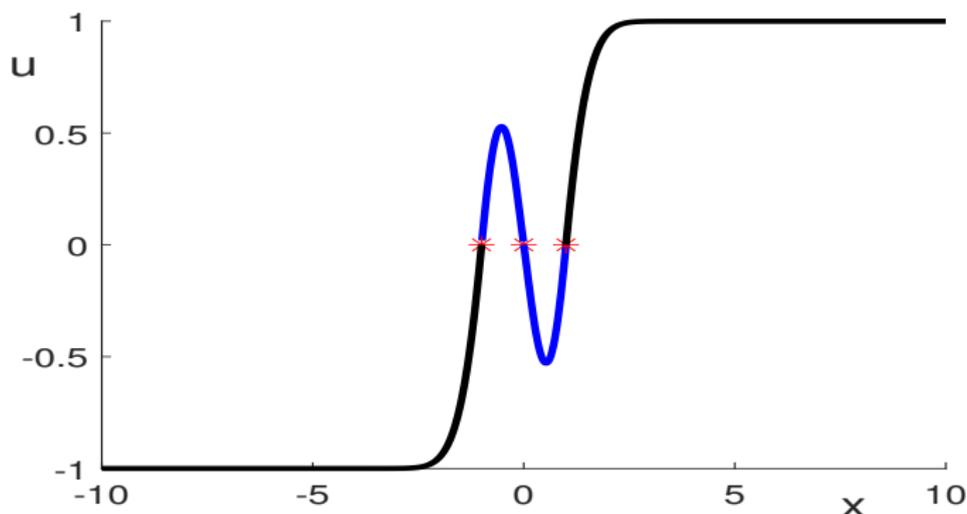


Convergence in time for L^2 -norm of perturbation



Initial data with multiple interfaces

Main question: Is there the finite-time extinction of the area between two consequent interfaces?



Interface at $x = 0$ persists for odd data. Interfaces at $x = \pm\xi(t)$ move.

A simple argument suggesting finite-time coalescence

Let $z(t, x) := 1 - u(t, x)$. It satisfies $z_t = -|1 - z|_x + z_{xx}$.

If $z(0, \cdot) : (0, \infty) \rightarrow \mathbb{R}$ is positive and integrable, then $z(t, \cdot) : (0, \infty) \rightarrow \mathbb{R}$ is positive and integrable for $t > 0$ by comparison principle.

We have for some time $t \in [0, \tau_0)$

$$0 < \xi(t) \leq \int_0^{\xi(t)} z(t, x) dx \leq \int_0^{\infty} z(t, x) dx =: M(t),$$

because $z(t, x) \geq 1$ for $x \in [0, \xi(t)]$ and $z(t, x) \geq 0$ for $x \in [\xi(t), \infty)$.

On the other hand,

$$\frac{dM}{dt} = -1 - z_x(t, 0) \leq -1.$$

Hence, $M(t) \leq M(0) - t$ and we have finite-time coalescence: $\xi(\tau_0) = 0$.

Reformulation for numerical approximations

The original problem is

$$\begin{cases} u_t = -u_x + u_{xx}, & u(t, x) < 0, & 0 < x < \xi(t), \\ u_t = u_x + u_{xx}, & u(t, x) > 0, & \xi(t) < x < \infty, \\ u(t, 0) = 0, & u(t, \xi(t)) = 0, & \lim_{x \rightarrow +\infty} u(t, x) = 1, \end{cases}$$

By using $y := x/\xi(t)$, the boundary-value problem is mapped to the time-independent regions:

$$\begin{cases} u_t = \xi^{-1}(\xi' y - 1)u_y + \xi^{-2}u_{yy}, & u(t, y) < 0, & 0 < y < 1, \\ u_t = \xi^{-1}(\xi' y + 1)u_y + \xi^{-2}u_{yy}, & u(t, y) > 0, & 1 < y < \infty, \\ u(t, 0) = 0, & u(t, 1) = 0, & \lim_{y \rightarrow +\infty} u(t, y) = 1, \end{cases}$$

closed with the interface condition:

$$\xi'(t) = -1 - \frac{u_{yy}(t, 1^+)}{\xi(t)u_y(t, 1)} = +1 - \frac{u_{yy}(t, 1^-)}{\xi(t)u_y(t, 1)}.$$

Remarks on the numerical method

- Central-difference approximation of spatial derivatives.
- The grid on $[0, 1]$ is complemented with the extra grid point $y_{N+1} = 1 + h$ and the approximation u_{N+1}^* . The grid on $[1, L]$ with $L = 10$ is complemented with the extra grid point $y_{N-1} = 1 - h$ and the approximation u_{N-1}^* . Note that $u_{N\pm 1}^* \neq u_{N\pm 1}$.
- The additional variables u_{N+1}^* and u_{N-1}^* are found from the interface conditions: $[u_y]_-^+(1) = 0$ and $[u_{yy}]_-^+(1) = -2\xi(t)|u_y(t, 1)|$. This yields the relation between linear advection-diffusion equation and

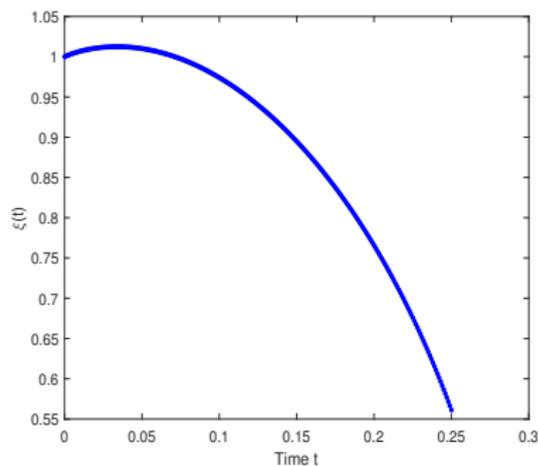
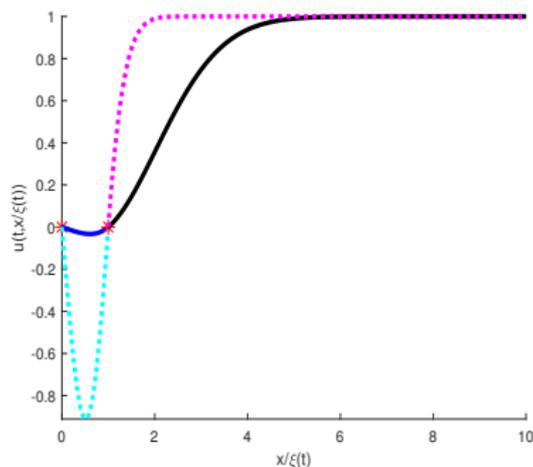
$$\xi'(t) = -\frac{(2 - h\xi)(u_{N+1} + u_{N-1})}{h\xi(u_{N+1} - u_{N-1})}.$$

- Time steps are performed with the implicit Crank-Nicholson method

Initial data and evolution: $\alpha = 1.5$

$$u_0(x) = \begin{cases} x(1-x)(ax^2 + bx + c), & 0 < x < 1, \\ 1 - e^{-\alpha(x^2-1)}, & 1 < x < \infty, \end{cases}$$

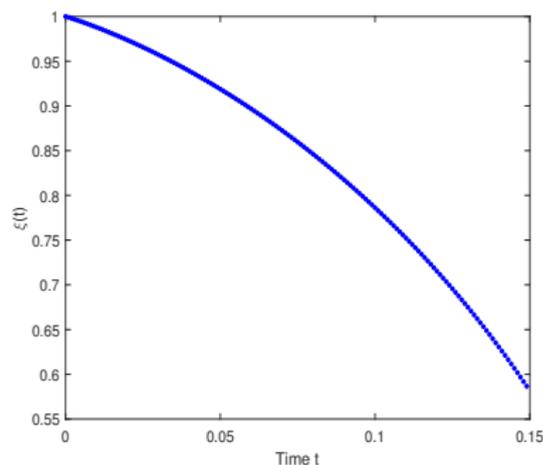
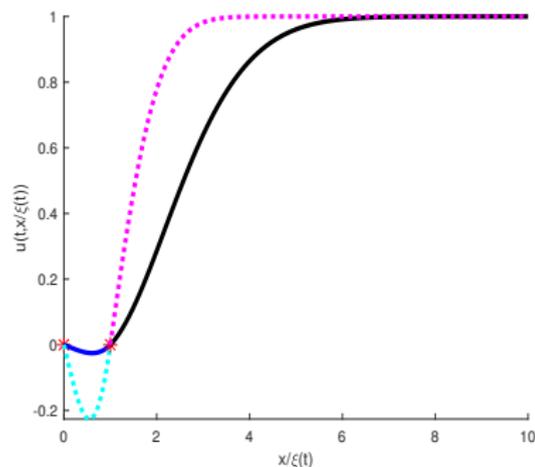
with $\xi'(0) = 2(\alpha - 1)$, where a , b , c are uniquely defined by α .



Initial data and evolution: $\alpha = 0.5$

$$u_0(x) = \begin{cases} x(1-x)(ax^2 + bx + c), & 0 < x < 1, \\ 1 - e^{-\alpha(x^2-1)}, & 1 < x < \infty, \end{cases}$$

with $\xi'(0) = 2(\alpha - 1)$, where a, b, c are uniquely defined by α .



Conjecture based on numerical data [P., de Rijk, 2023]

There exists $t_0 \in (0, \infty)$ such that

$$\xi(t) \sim \sqrt{t_0 - t}, \quad u_x(t, \xi(t)) \sim (t_0 - t), \quad u_{xx}(t, \xi(t)^-) \sim \sqrt{t_0 - t}.$$

This is in agreement with

$$\xi'(t) = +1 - \frac{u_{xx}(t, \xi(t)^-)}{u_x(t, 1)}.$$

Furthermore, we conjecture

$$\left| \int_0^{\xi(t)} u(t, x) dx \right| \sim (t_0 - t)^2, \quad \int_0^{\xi(t)} u^2(t, x) dx \sim \sqrt{(t_0 - t)^7},$$

in agreement with the balance laws

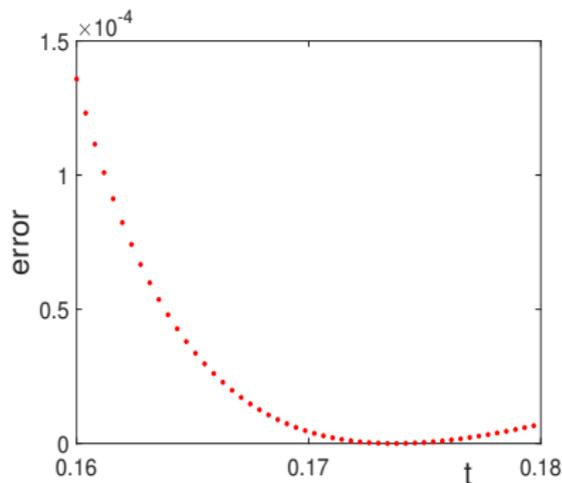
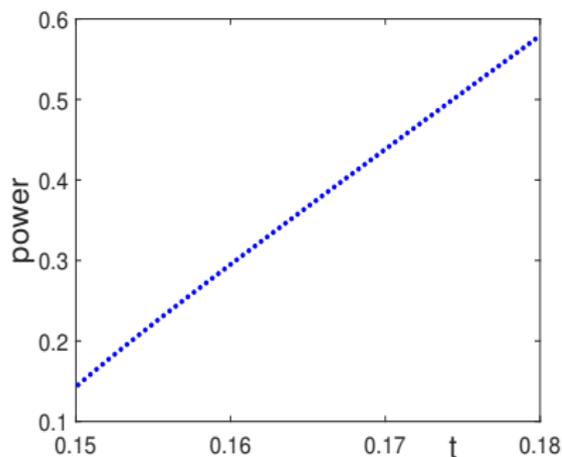
$$\frac{d}{dt} \int_0^{\xi(t)} u dx = u_x(t, \xi(t)) - u_x(t, 0), \quad \frac{d}{dt} \int_0^{\xi(t)} u^2 dx = -2 \int_0^{\xi(t)} u_x^2 dx.$$

The method of data extraction, e.g. for $\xi(t) \sim \sqrt{t_0 - t}$

For a fixed value of t_0 (past the termination time of our computations), we compute c_1 (left) and c_2 in the linear regression

$$\log(\xi(t)) \quad \text{versus} \quad c_1 \log(t_0 - t) + c_2$$

as well as the approximation error (right). The minimal error of 10^{-9} is attained at $t_0 = 0.17$ with $c_1 = 0.492$.



Summary

- Evolution of the modular Burgers equation is considered.
- Asymptotic stability of a traveling viscous shock is proven and illustrated numerically.
- It is shown that shock waves with multiple interfaces extinct in a finite time due to finite-time coalescence of interfaces
- A precise scaling law of the finite-time coalescence is suggested based on the numerical data.

Open question

- 1 Numerical approximations of shock waves with multiple interfaces as a problem with moving boundaries.
- 2 Numerical approximation of solitary waves with multiple interfaces in the modular KdV equation.
- 3 Analytical proof of well-posedness of the linear evolution with multiple interfaces.
- 4 Analytical proof of the precise scaling law of the finite-time coalescence.
- 5 Expanding methods to the Burgers and KdV models with logarithmic nonlinearities...

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