

## Transformations

A **transformation**  $T$  from  $\mathbf{R}^n$  to  $\mathbf{R}^m$  is a rule such that for every vector  $\mathbf{u} \in \mathbf{R}^n$  there exists a vector  $T(\mathbf{u}) \in \mathbf{R}^m$ . The transformation is denoted as  $T : \mathbf{R}^n \mapsto \mathbf{R}^m$ , where  $\mathbf{R}^n$  is the **domain** of  $T$  and  $\mathbf{R}^m$  is the **range** (image) of  $T$ .

## Examples

- Projection from  $\mathbf{R}^3$  to the  $(x, y)$ -plane

$$\mathbf{u} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}, \quad T(\mathbf{u}) = \begin{bmatrix} x \\ y \end{bmatrix}.$$

- Reflection of  $\mathbf{R}^3$  about the origin

$$\mathbf{u} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}, \quad T(\mathbf{u}) = \begin{bmatrix} -x \\ -y \\ -z \end{bmatrix}.$$

A transformation  $T : \mathbf{R}^n \mapsto \mathbf{R}^m$  is called **linear** if

(T1)  $T(\mathbf{u} + \mathbf{v}) = T(\mathbf{u}) + T(\mathbf{v})$  for all  $\mathbf{u}, \mathbf{v} \in \mathbf{R}^n$ ;

(T2)  $T(k\mathbf{u}) = kT(\mathbf{u})$  for all  $\mathbf{u} \in \mathbf{R}^n$  and all  $k \in \mathbf{R}$ .

Theorem:

Every linear transformation  $T : \mathbf{R}^n \mapsto \mathbf{R}^m$  can be expressed by a matrix multiplication with an  $n \times m$  matrix.

## List of particular transformations

1. Projection of a vector on  $\mathbf{R}^2$  to the vector  $\mathbf{d} \in \mathbf{R}^2$

$$\mathbf{d} = \begin{pmatrix} d_1 \\ d_2 \end{pmatrix}, \quad P_{\mathbf{d}}(\mathbf{u}) = \text{proj}_{\mathbf{d}}(\mathbf{u}) = \frac{\mathbf{d} \cdot \mathbf{u}}{\|\mathbf{d}\|^2} \mathbf{d}$$

2. Reflection of a vector on  $\mathbf{R}^2$  about the vector  $\mathbf{d} \in \mathbf{R}^2$

$$\mathbf{d} = \begin{pmatrix} d_1 \\ d_2 \end{pmatrix}, \quad Q_{\mathbf{d}}(\mathbf{u}) = 2P_{\mathbf{d}}(\mathbf{u}) - \mathbf{u}.$$

3. Dilation and  $x,y$ -dilations of a vector on  $\mathbf{R}^2$

$$D_k(\mathbf{u}) = k\mathbf{u}$$

and

$$D_{x,k}(\mathbf{u}) = \begin{pmatrix} kx \\ y \end{pmatrix}, \quad D_{y,k}(\mathbf{u}) = \begin{pmatrix} x \\ ky \end{pmatrix},$$

4. Translation of a vector on  $\mathbf{R}^2$  in the direction of the vector  $\mathbf{d} \in \mathbf{R}^2$

$$T_{\mathbf{d}}(\mathbf{u}) = \mathbf{u} + \mathbf{d}$$