

# Existence of breathers (modulating pulses) in periodic systems via spatial dynamics

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# Section 1

## Workshop in honor of Michael Plum

- ▷ First meeting: July 2016 in LMS Durham Symposium
- ▷ Extended visit: KIT, January-July 2022 (Humboldt Award)
- ▷ Shorter meetings in 2023

- ▷ A. Contreras, D.E. Pelinovsky, and M. Plum, Orbital stability of domain walls in coupled Gross-Pitaevskii systems, *SIAM J. Math. Anal.* **50** (2018) 810–833
- ▷ D.E. Pelinovsky and M. Plum, “Dynamics of black solitons in a regularized nonlinear Schrodinger equation”, *Proceeding AMS* **152** (2024) 1217–1231
- ▷ D.E. Pelinovsky and M. Plum, “Stability of black solitons in optical systems with intensity-dependent dispersion”, *SIAM J. Math. Anal.* (2024) in print



## Section 2

# Breathers and Modulating pulses

## Examples of a breather

The standard example is the breather of the sine–Gordon equation:

$$u_{tt} - u_{xx} + \sin(u) = 0,$$

given by the exact solution

$$u(x, t) = 4 \arctan \frac{\sqrt{1 - \omega^2} \cos(\omega t)}{\omega \cosh(\sqrt{1 - \omega^2} x)}, \quad 0 < \omega < 1.$$

This is the standing breather which also generates a family of moving breathers by the Lorentz transformation:

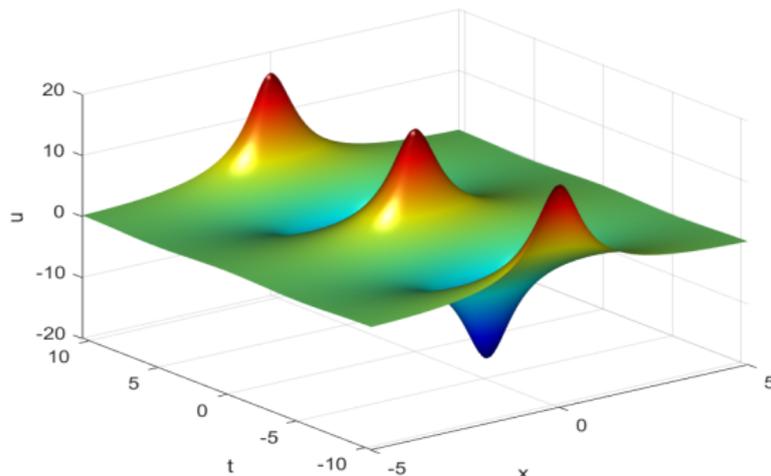
$$u(x, t) = \tilde{u} \left( \frac{x - ct}{\sqrt{1 - c^2}}, \frac{t - cx}{\sqrt{1 - c^2}} \right), \quad -1 < c < 1.$$

# Examples of a breather

The breather solution satisfies

$$u(x, t + T) = u(x, t) \quad \text{and} \quad \lim_{|x| \rightarrow \infty} u(x, t) = 0,$$

with  $T = 2\pi/\omega$ .



## Examples of a breather

One striking asymptotic limit is the small-amplitude, slow-scale approximation:

$$u(x, t) = 4 \arctan \frac{\sqrt{1 - \omega^2} \cos(\omega t)}{\omega \cosh(\sqrt{1 - \omega^2} x)}, \quad \omega \in (0, 1).$$

If  $\varepsilon := \sqrt{1 - \omega^2}$  is small, then the power expansions yields

$$u(x, t) = 4\varepsilon \operatorname{sech}(\varepsilon x) \cos(\omega(\varepsilon)t) + \mathcal{O}(\varepsilon^3),$$

with

$$\omega(\varepsilon) = \sqrt{1 - \varepsilon^2} = 1 - \frac{1}{2}\varepsilon^2 + \mathcal{O}(\varepsilon^4).$$

## Small-amplitude expansions

This suggest the reduction of the sine–Gordon equation

$$u_{tt} - u_{xx} + \sin(u) = 0,$$

with the small-amplitude, slow-scale expansions

$$u(x, t) = \varepsilon[A(\varepsilon x, \varepsilon^2 t)e^{it} + \bar{A}(\varepsilon x, \varepsilon^2 t)e^{-it}] + \mathcal{O}(\varepsilon^3).$$

Since  $\sin(u) = u - \frac{1}{6}u^3 + \mathcal{O}(u^5)$  and  $e^{\pm it}$  are in the null space of  $1 + \partial_t^2$  in  $L_{\text{per}}^2$ , we get the NLS equation for  $A = A(\xi, \tau)$  from the solvability condition in  $L_{\text{per}}^2$  at the order of  $\mathcal{O}(\varepsilon^3)$ :

$$2iA_\tau - A_{\xi\xi} - \frac{1}{2}|A|^2A = 0.$$

The breather corresponds to the NLS soliton  $A(\xi, \tau) = 2\text{sech}(\xi)e^{-\frac{i}{2}\tau}$ .

## Small-amplitude expansions

However, the expansions fail for non-integrable versions of the wave equation, e.g. for the  $\phi^4$  theory:

$$u_{tt} - u_{xx} + u - \frac{1}{6}u^3 = 0.$$

- ▷ H. Segur, M. D. Kruskal, Phys. Rev. Lett. 58 (1987), 747
- ▷ J. Denzler, Commun. Math. Phys. 158 (1993) 397
- ▷ B. Birnir, H.P. McKean, A. Weinstein, CPAM 47 (1994) 1043
- ▷ Justification of the NLS approximation holds only on long but finite time intervals:

$$\sup_{t \in [0, \tau_0 \varepsilon^{-2}]} \|u(\cdot, t) - \varepsilon A(\varepsilon \cdot, \varepsilon^2 t) e^{it} - \varepsilon \bar{A}(\varepsilon \cdot, \varepsilon^2 t) e^{-it}\|_{L^\infty} \leq C \varepsilon^3.$$

## Small-amplitude expansions

The breather solutions can be thought to be a solution of the form

$$u(x, t) = v(\xi, \theta), \quad \xi := x - ct, \quad \theta := kx - \omega t$$

for some appropriately chosen parameters  $c, k, \omega$  and with boundary conditions

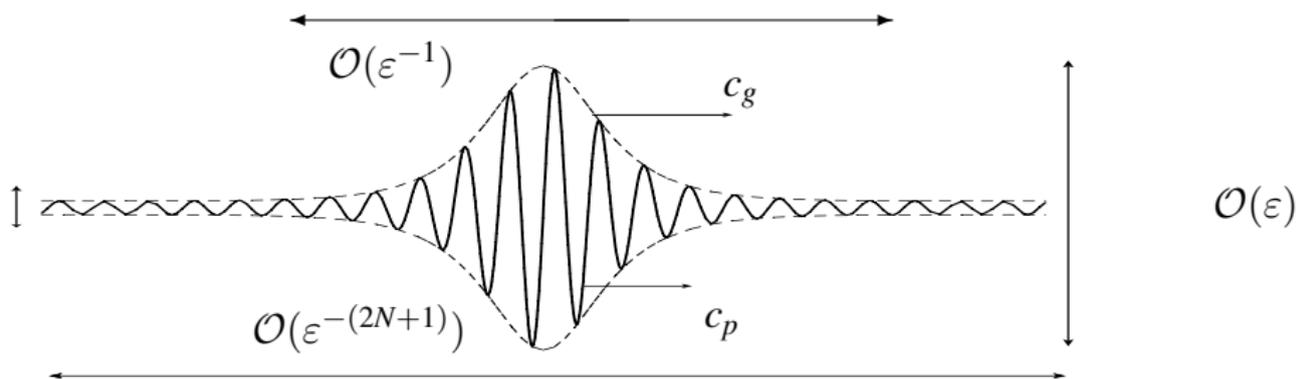
$$u(x, \theta + 2\pi) = u(x, \theta) \quad \text{and} \quad \lim_{|\xi| \rightarrow \infty} v(\xi, \theta) = 0.$$

The PDE is converted to the spatial dynamical system in  $\xi$  by using Fourier series in  $\theta$ . A center manifold does not allow us generally to construct a homoclinic orbit with zero boundary conditions.

- ▷ M. Groves and G. Schneider, *Comm. Math. Phys.* 219 (2001); *J. Diff. Eqs.* 219 (2005); *Comm. Math. Phys.* 278 (2008).

## Small-amplitude expansions

Instead of breathers, we would then have modulating pulses which are not truly localized (also called generalized breathers).



Besides integrable systems, true breathers exist in some models:

- ▷ Lattices with weak coupling:

$$\ddot{u}_n - \epsilon^2(\Delta u)_n + u_n + u_n^3 = 0, \quad n \in \mathbb{Z}.$$

S. Aubry & R. MacKay (1994); D.P., T. Penati, S. Paleari (2020)

- ▷ Systems with periodic coefficients

$$s(x)u_{tt} - u_{xx} - \rho(x)u + u^3 = 0, \quad s(x+2\pi) = s(x), \quad \rho(x+2\pi) = \rho(x).$$

C. Blank, M. Chirilus, V. Lescarret, G. Schneider (2011);

A. Hirsch & W. Reichel (2019); S. Kohler & W. Reichel (2022)

- ▷ Curl–curl wave equations: M. Plum & W. Reichel (2016), (2023)

In more general models, modulating pulses exist instead of breathers:

- ▷ Standing modulating pulse solutions of the wave equation with periodic coefficients

$$u_{tt} - u_{xx} - \rho(x)u + u^3 = 0, \quad \rho(x + 2\pi) = \rho(x).$$

V. Lescarret, G. Schneider (2009); T. Dohnal, D. Rudolf (2020)

- ▷ Traveling modulating pulse solutions of the Gross-Pitaevskii equation with periodic potentials:

$$i\psi_t = -\psi_{xx} + \rho(x)\psi + |\psi|^2\psi, \quad \rho(x + 2\pi) = \rho(x)$$

D.P & G. Schneider (2008); D.P. (2011);

# Breathers versus modulating pulses

No results for traveling modulating pulse solutions in the wave equation with periodic coefficients so far.

$$u_{tt} - u_{xx} + \rho(x)u = \gamma u^3, \quad \rho(x + 2\pi) = \rho(x).$$

Here traveling modulating pulses have three spatial scales:

$$\xi = x - ct, \quad \theta = kx - \omega t, \quad x.$$

T. Dohnal, D.P., G. Schneider, Nonlinearity (2024) under review.

## Section 3

# Traveling modulating pulses in the wave equation with periodic coefficients

# Linear theory and traveling modulating pulses

Consider the linear wave equation

$$\partial_t^2 u(x, t) - \partial_x^2 u(x, t) + \rho(x)u(x, t) = 0, \quad \rho(x + 2\pi) = \rho(x),$$

with  $2\pi$ -periodic, bounded, and positive coefficient  $\rho$ .

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Solutions are given by the family of Bloch modes:

$$u(x, t) = e^{\pm i\omega_n(l)t} e^{ilx} f_n(l, x), \quad n \in \mathbb{N}, \quad l \in \mathbb{B} := \mathbb{R} \setminus \mathbb{Z},$$

where  $f_n(l, x) = f_n(l, x + 2\pi)$  and  $f_n(l, x) = f_n(l + 1, x)e^{ix}$  are  $L^2([0, 2\pi])$  normalized eigenfunctions and

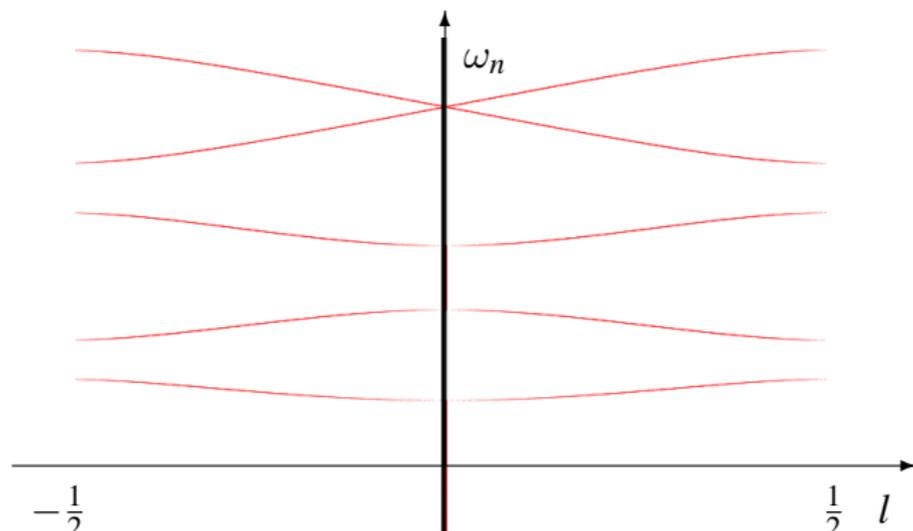
$$0 < \omega_1(l) \leq \omega_2(l) \leq \dots \leq \omega_n(l) \leq \omega_{n+1}(l) \leq \dots \quad \forall l \in \mathbb{B},$$

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with  $2\pi$ -periodic, bounded, and positive coefficient  $\rho$ .

For fixed  $n_0 \in \mathbb{N}$  and  $l_0 \in \mathbb{B}$ , we can approximate the traveling modulating pulse by

$$u_{\text{app}}(x, t) = \varepsilon A(\varepsilon(x - c_g t), \varepsilon^2 t) f_{n_0}(l_0, x) e^{il_0 x} e^{-i\omega_{n_0}(l_0)t} + c.c.,$$

where  $c_g = \omega'_{n_0}(l_0)$ , and  $A = A(X, T)$  is a soliton of the NLS equation:

$$2i\partial_T A + \omega''_{n_0}(l_0)\partial_X^2 A + \gamma_{n_0}(l_0)|A|^2 A = 0,$$

with  $\gamma_{n_0}(l_0) = 3\|f_{n_0}(l_0, \cdot)\|_{L^4}^4 / \omega_{n_0}(l_0)$ .

## Main theorem [T. Dohnal, D.P., G. Schneider (2024)]

Choose  $n_0 \in \mathbb{N}$  and  $l_0 \in \mathbb{B}$  such that  $\omega_n(l_0) \neq \omega_{n_0}(l_0), \forall n \neq n_0$ ,  
 $\omega'_{n_0}(l_0) \neq \pm 1, \omega''_{n_0}(l_0) \neq 0$ , and

$$\omega_n^2(ml_0) \neq m^2\omega_{n_0}^2(l_0), \quad m \in \{3, 5, \dots, 2N + 1\}, \quad \forall n \in \mathbb{N}.$$

There are  $\varepsilon_0 > 0$  and  $C > 0$  such that for all  $\varepsilon \in (0, \varepsilon_0)$  there exist traveling modulating pulse solutions of the semi-linear wave equation:

$$u(x, t) = v(\xi, z, x) \quad \text{with} \quad \xi = x - c_g t, \quad z = l_0 x - \omega t,$$

with  $v \in C^2([- \varepsilon^{-(2N+1)}, \varepsilon^{-(2N+1)}], \mathcal{X})$  satisfying

$$\sup_{\xi \in [- \varepsilon^{-(2N+1)}, \varepsilon^{-(2N+1)}]} |v(\xi, z, x) - h(\xi, z, x)| \leq C\varepsilon^{2N},$$

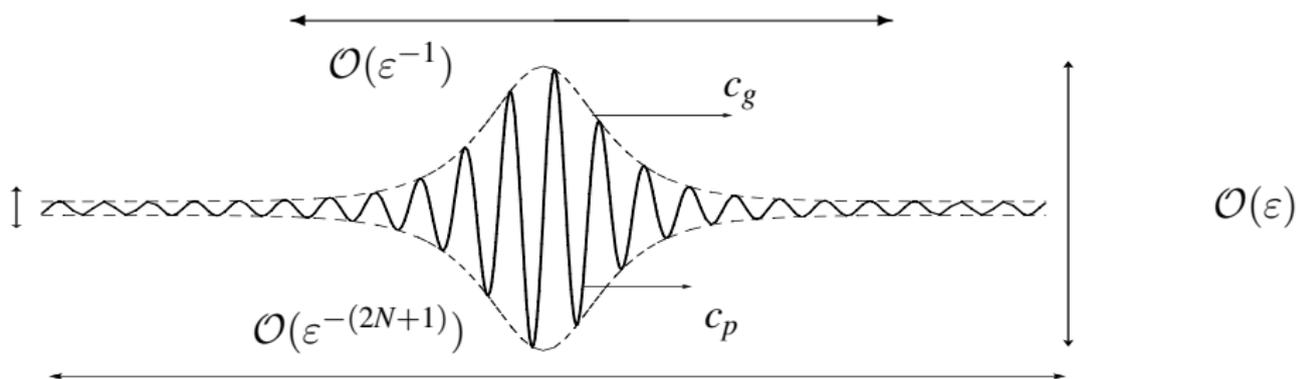
where  $\mathcal{X} := H_{\text{per}}^2(\mathbb{T}, L^2(\mathbb{T})) \cap H_{\text{per}}^1(\mathbb{T}, H_{\text{per}}^1(\mathbb{T})) \cap L^2(\mathbb{T}, H_{\text{per}}^2(\mathbb{T}))$ .

The function  $h \in C^2(\mathbb{R}, \mathcal{X})$  satisfies

$$\lim_{|\xi| \rightarrow \infty} h(\xi, z, x) = 0 \quad \text{and} \quad \sup_{\xi, z, x \in \mathbb{R}} |h(\xi, z, x) - u_{\text{app}}(\xi, z, x)| \leq C\varepsilon^2.$$

## Some remarks about the main result

The illustration of the main result is the same picture:



## Some remarks about the main result

As a consequence, the modulating pulses are relevant for the initial-value problem for the wave equation.

### Theorem

Let  $v$  be the constructed solution and take an arbitrary function  $\phi \in C^2(\mathbb{R} \setminus [-\varepsilon^{-(2N+1)}, \varepsilon^{-(2N+1)}], \mathcal{X})$  such that

$$v_{\text{ext}}(\xi, z, x) := \begin{cases} v(\xi, x, z), & (\xi, x, z) \in [-\varepsilon^{-(2N+1)}, \varepsilon^{-(2N+1)}] \times \mathbb{R} \times \mathbb{R}, \\ \phi(\xi, x, z), & (\xi, x, z) \in \text{otherwise} \end{cases}$$

satisfies  $v_{\text{ext}} \in C^2(\mathbb{R}, \mathcal{X})$ . Let  $u_0(x) := v_{\text{ext}}(x, \ell_0 x, x)$  and

$$u_1(x) := -c_g \partial_\xi v_{\text{ext}}(x, \ell_0 x, x) - \omega \partial_z v_{\text{ext}}(x, \ell_0 x, x).$$

The corresponding solution of the wave equation satisfies

$u(x, t) = v(x - c_g t, \ell_0 x - \omega t, x)$  for every

$(x, t) \in [-\varepsilon^{-(2N+1)}, \varepsilon^{-(2N+1)}] \times (0, \infty)$  with  $|x| + t < \varepsilon^{-2N+1}$ .

# Spatial dynamics formulation

Starting with the wave equation

$$\partial_t^2 u(x, t) - \partial_x^2 u(x, t) + \rho(x)u(x, t) = \gamma u(x, t)^3, \quad \rho(x + 2\pi) = \rho(x),$$

we introduce three spatial scales in

$$u(x, t) = v(\xi, z, x) \quad \text{with} \quad \xi = x - c_g t, \quad z = l_0 x - \omega t.$$

This yields

$$\begin{aligned} & [(c^2 - 1)\partial_\xi^2 + 2(c\omega - l_0)\partial_\xi\partial_z - 2\partial_\xi\partial_x + (\omega^2 - l_0^2)\partial_z^2 - 2l_0\partial_z\partial_x - \partial_x^2] v \\ & + \rho(x)v = \gamma v^3, \end{aligned}$$

with  $v(\xi, z + 2\pi, x) = v(\xi, z, x + 2\pi) = v(\xi, z, x)$ . We can use the Fourier series in  $z$  but not in  $x$ .

## Spatial dynamics formulation

By using Fourier series in  $z$  and writing the first-order system in  $\xi$ , we obtain the spatial dynamical system:

$$(1-c^2)\partial_\xi \begin{pmatrix} \tilde{v}_m \\ \tilde{w}_m \end{pmatrix} = A_m(\omega, c) \begin{pmatrix} \tilde{v}_m \\ \tilde{w}_m \end{pmatrix} - \gamma \begin{pmatrix} 0 \\ (\tilde{v} * \tilde{v} * \tilde{v})_m \end{pmatrix}, \quad m \in \mathbb{Z},$$

where

$$A_m(\omega, c) = \begin{pmatrix} 0 & 1 \\ -(\partial_x + iml_0)^2 + \rho(x) - m^2\omega^2 & 2imc\omega - 2(\partial_x + iml_0) \end{pmatrix}.$$

For each  $m \in \mathbb{Z}$ ,  $A_m(\omega, c) : D \subset R \rightarrow R$  are linear operators with

$$D = H_{\text{per}}^2(\mathbb{T}) \times H_{\text{per}}^1(\mathbb{T}), \quad R = H_{\text{per}}^1(\mathbb{T}) \times L^2(\mathbb{T})$$

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We are looking for the solution map

$[0, \xi_0] \ni \xi \mapsto (\tilde{v}_m, \tilde{w}_m)_{m \in \mathbb{Z}} \in C^1([0, \xi_0], \mathcal{D})$  in function space

$$\begin{aligned} \mathcal{D} := & [\ell^{2,2}(\mathbb{Z}, L^2(\mathbb{T})) \cap \ell^{2,1}(\mathbb{Z}, H_{\text{per}}^1(\mathbb{T})) \cap \ell^{2,0}(\mathbb{Z}, H_{\text{per}}^2(\mathbb{T}))] \\ & \times [\ell^{2,1}(\mathbb{Z}, L^2(\mathbb{T})) \cap \ell^{2,0}(\mathbb{Z}, H_{\text{per}}^1(\mathbb{T}))]. \end{aligned}$$

## Eigenvalues of the spatial system

Recall that the bifurcation case corresponds to  $\omega_0 = \omega_{n_0}(l_0)$  and  $c_g = \omega'_{n_0}(l_0)$ . The eigenvalue problem  $A_m(\omega_0, c_g)\vec{V} = \lambda\vec{V}$  is reformulated in the scalar form:

$$[-(\partial_x + iml_0 + \lambda)^2 + \rho(x)]V(x) = (m\omega_0 - ic_g\lambda)^2V(x),$$

which is solved with Bloch eigenfunctions in

$$\omega_n^2(ml_0 - i\lambda) = (m\omega_0 - ic_g\lambda)^2, \quad n \in \mathbb{N}.$$

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$$\omega_n^2(ml_0 - i\lambda) = (m\omega_0 - ic_g\lambda)^2, \quad n \in \mathbb{N}.$$

No information on roots of  $\lambda$  is available, but zero roots  $\lambda = 0$  are controlled from the non-resonance conditions  $\omega_n(l_0) \neq \omega_0$ ,  $n \neq n_0$ ,

$$\omega_n^2(ml_0) \neq m^2\omega_0^2, \quad m \in \{3, 5, \dots, 2N + 1\}, \quad \forall n \in \mathbb{N}.$$

**The zero root  $\lambda = 0$  is double in the subspace  $n = n_0$ .**

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$$\omega_n^2(ml_0 - i\lambda) = (m\omega_0 - ic_g\lambda)^2, \quad n \in \mathbb{N}.$$

One can show that the non-resonance conditions can be satisfied for  $\rho(x) = 1$  (low-contrast potentials). In this case, the roots are defined by the quadratic equations

$$1 + (n + ml_0 - i\lambda)^2 = (m\omega_0 - ic_g\lambda)^2.$$

**Moreover, one can find conditions when all roots are simple.**

# Algorithm for justification of a homoclinic orbit

**Step 1: Decomposition near the bifurcation.**

$$\begin{pmatrix} \tilde{v}_1(\xi, x) \\ \tilde{w}_1(\xi, x) \end{pmatrix} = \underbrace{\varepsilon q_0(\xi)F_0(x) + \varepsilon q_1(\xi)F_1(x)} + \varepsilon S_1(\xi, x),$$

and

$$\begin{pmatrix} \tilde{v}_m(\xi, x) \\ \tilde{w}_m(\xi, x) \end{pmatrix} = \varepsilon S_m(\xi, x), \quad m \neq 1,$$

where the small parameter is defined for  $\omega = \omega_0 + \varepsilon^2$  and  $c = c_g$ .

# Algorithm for justification of a homoclinic orbit

**Step 2: Near-identity transformation to reduce the residual terms.**

They are performed based on the bounds

$$\|(\Pi A_1(\omega_0, c_g) \Pi)^{-1}\|_{R \rightarrow D} + \sum_{m=3}^{2N+1} \|A_m(\omega_0, c_g)^{-1}\|_{R \rightarrow D} \leq C_0,$$

which is obtained from the resolvent equations

$$\begin{pmatrix} 0 & 1 \\ L_m & M_m \end{pmatrix} \begin{pmatrix} v \\ w \end{pmatrix} = \begin{pmatrix} f \\ g \end{pmatrix},$$

with

$$\begin{aligned} L_m &= -(\partial_x + iml_0)^2 + \rho(x) - m^2\omega_0^2, \\ M_m &= 2imc_g\omega_0 - 2(\partial_x + iml_0), \end{aligned}$$

# Algorithm for justification of a homoclinic orbit

After Steps 1 and 2, the system

$$\frac{d}{d\xi} \begin{pmatrix} q_0 \\ q_1 \end{pmatrix} = \begin{pmatrix} q_1 \\ 0 \end{pmatrix} + \varepsilon^2 F(q_0, q_1, \mathbf{S})$$

$$\frac{d}{d\xi} S_m = A_m(\omega_0, c_g) S_n + \varepsilon^2 F_m(q_0, q_1, \mathbf{S})$$

becomes

$$\frac{d}{d\xi} \begin{pmatrix} q_0 \\ q_1 \end{pmatrix} = \begin{pmatrix} q_1 \\ 0 \end{pmatrix} + \sum_{j=1}^N \varepsilon^{2j} F^{(j)}(q_0, q_1) + \varepsilon^{2N+2} F^{(N)}(q_0, q_1, \mathbf{S})$$

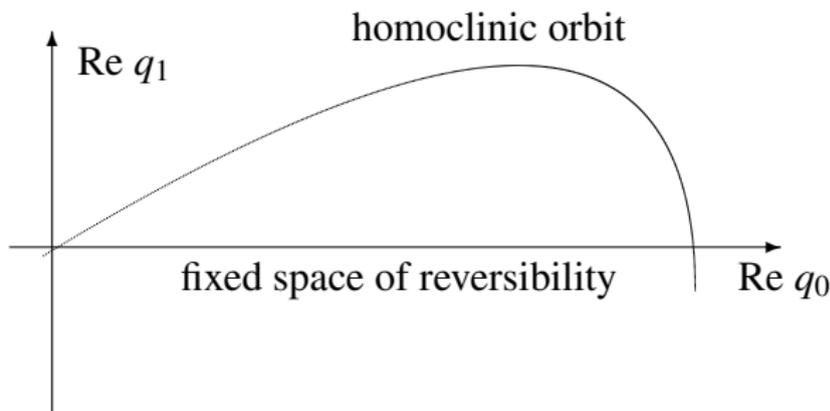
$$\frac{d}{d\xi} S_m = A_m(\omega_0, c_g) S_n + \varepsilon^{2N+2} F_m(q_0, q_1) + \varepsilon^2 \tilde{F}_m(q_0, q_1, \mathbf{S})$$

# Algorithm for justification of a homoclinic orbit

## Step 3: Construction of a reversible homoclinic orbit

$$\frac{d}{d\xi} \begin{pmatrix} q_0 \\ q_1 \end{pmatrix} = \begin{pmatrix} q_1 \\ 0 \end{pmatrix} + \sum_{j=1}^N \varepsilon^{2j} F^{(j)}(q_0, q_1)$$

satisfying  $\text{Im}(q_0) = 0$  and  $\text{Re}(q_1) = 0$ .



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satisfying  $\text{Im}(q_0) = 0$  and  $\text{Re}(q_1) = 0$ .

We have the leading-order approximation with

$$\|q_0 - A(\varepsilon \cdot)\|_{L^\infty} \leq C\varepsilon, \quad \|q_1 - \varepsilon A'(\varepsilon \cdot)\|_{L^\infty} \leq C\varepsilon^2,$$

The persistence analysis is done by the implicit function theorem in  $H^1(\mathbb{R})$  because of the symmetries of the truncated system with the 2-parameter family of solutions

$$(q_0(\xi + \xi_0)e^{i\theta_0}, q_1(\xi + \xi_0)e^{i\theta_0}), \quad \xi_0, \theta_0 \in \mathbb{R}.$$

## Algorithm for justification of a homoclinic orbit

After Step 3, we can write  $(q_0, q_1) = (Q_0, \varepsilon Q_1) + (q_0, \varepsilon q_1)$ , where  $(Q_0, \varepsilon Q_1)$  is the homoclinic orbit of the truncated system. The abstract system is

$$\begin{aligned}\partial_\xi \mathbf{c}_{0,r} &= \varepsilon \Lambda_0(\xi) \mathbf{c}_{0,r} + \varepsilon \mathbf{G}(\mathbf{c}_{0,r}, \mathbf{c}_r) + \varepsilon^{2N+1} \mathbf{G}_R(\mathbf{c}_{0,hom} + \mathbf{c}_{0,r}, \mathbf{c}_r), \\ \partial_\xi \mathbf{c}_r &= \Lambda_r \mathbf{c}_r + \varepsilon^2 \mathbf{F}(\mathbf{c}_{0,hom} + \mathbf{c}_{0,r}, \mathbf{c}_r) + \varepsilon^{2N+2} \mathbf{F}_R(\mathbf{c}_{0,hom} + \mathbf{c}_{0,r}, \mathbf{c}_r),\end{aligned}$$

$\Lambda_r$  contains nonzero eigenvalues for stable, center, and unstable manifolds of the linearized system. We assume

$$\begin{aligned}\|e^{\Lambda_s \xi}\|_{\mathcal{D} \rightarrow \mathcal{D}} &\leq K, & \xi &\geq 0, \\ \|e^{\Lambda_u \xi}\|_{\mathcal{D} \rightarrow \mathcal{D}} &\leq K, & \xi &\leq 0, \\ \|e^{\Lambda_c \xi}\|_{\mathcal{D} \rightarrow \mathcal{D}} &\leq K, & \xi &\in \mathbb{R}.\end{aligned}$$

## Algorithm for justification of a homoclinic orbit

After Step 3, we can write  $(q_0, q_1) = (Q_0, \varepsilon Q_1) + (q_0, \varepsilon q_1)$ , where  $(Q_0, \varepsilon Q_1)$  is the homoclinic orbit of the truncated system. The abstract system is

$$\begin{aligned}\partial_\xi \mathbf{c}_{0,r} &= \varepsilon \Lambda_0(\xi) \mathbf{c}_{0,r} + \varepsilon \mathbf{G}(\mathbf{c}_{0,r}, \mathbf{c}_r) + \varepsilon^{2N+1} \mathbf{G}_R(\mathbf{c}_{0,hom} + \mathbf{c}_{0,r}, \mathbf{c}_r), \\ \partial_\xi \mathbf{c}_r &= \Lambda_r \mathbf{c}_r + \varepsilon^2 \mathbf{F}(\mathbf{c}_{0,hom} + \mathbf{c}_{0,r}, \mathbf{c}_r) + \varepsilon^{2N+2} \mathbf{F}_R(\mathbf{c}_{0,hom} + \mathbf{c}_{0,r}, \mathbf{c}_r),\end{aligned}$$

**Step 4: Center-stable manifold.** For every  $\mathbf{a} \in \mathcal{D}_c$ ,  $\mathbf{b} \in \mathcal{D}_s$  s.t.

$\|\mathbf{a}\|_{\mathcal{D}_c} + \|\mathbf{b}\|_{\mathcal{D}_s} \leq C\varepsilon^{2N}$ , there exists a family of local solutions with

$$\sup_{\xi \in [0, \varepsilon^{-(2N+1)}]} (\|\mathbf{c}_{0,r}(\xi)\|_{C^4} + \|\mathbf{c}_c(\xi)\|_{\mathcal{D}_c} + \|\mathbf{c}_s(\xi)\|_{\mathcal{D}_s} + \|\mathbf{c}_u(\xi)\|_{\mathcal{D}_u}) \leq C\varepsilon^{2N},$$

satisfying  $\mathbf{c}_c(0) = \mathbf{a}$  and  $e^{-\xi_0 \Lambda_s} \mathbf{c}_s(\xi_0) = \mathbf{b}$  at  $\xi_0 = \varepsilon^{-(2N+1)}$ . These parameters are chosen to satisfy the reversibility constraints.

# Section 4

## Breathers localized in time

## Example: the focusing NLS equation

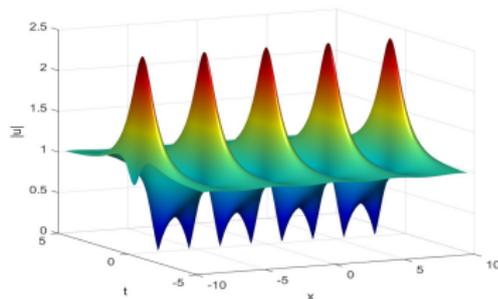
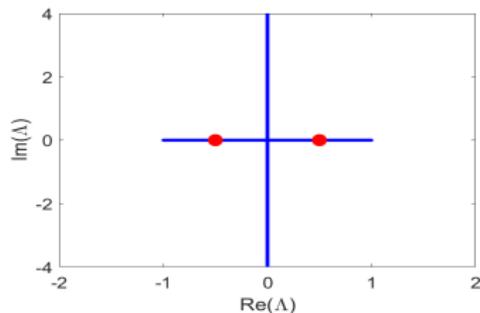
The focusing nonlinear Schrödinger (NLS) equation

$$i\partial_t\psi + \partial_x^2\psi + |\psi|^2\psi = 0$$

admits the exact solution [Akhmediev, Eleonsky, & Kulagin (1985)]

$$\psi(x, t) = e^{it} \left[ 1 - \frac{2(1 - \lambda^2) \cosh(k\lambda t) + ik\lambda \sinh(k\lambda t)}{\cosh(k\lambda t) - \lambda \cos(kx)} \right],$$

commonly known as Akhmediev breathers.



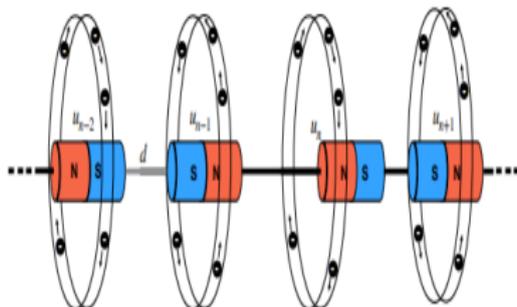
# The engineering setup

The FPU model:

$$\underline{m}\ddot{u}_n + k(t)u_n = \beta(d + u_n - u_{n-1})^{-\alpha} - \beta(d + u_{n+1} - u_n)^{-\alpha},$$

where  $\alpha, \beta, \underline{m}, d > 0$  and  $k(t + 2\pi) = k(t)$ .

FPU models a chain of repelling magnets surrounded by time modulated coils (Chong, Kim, Daraios et al.: arXiv:2310.06934)



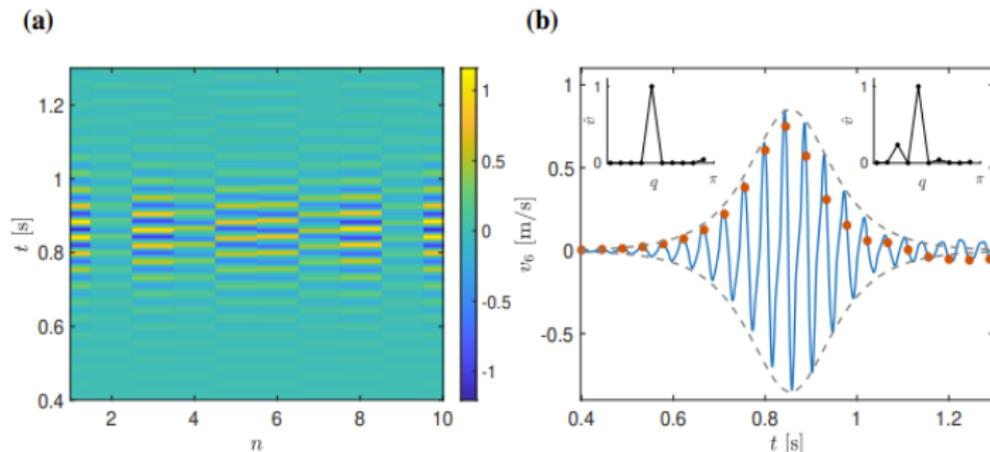
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Time-localized breathers were observed in experiments:



## Bifurcation theory

For  $N$  particles with Dirichlet conditions  $u_0 = u_{N+1} = 0$ , we use the discrete Fourier sine modes:

$$u_n(t) = \sum_{m=1}^N \hat{u}_m(t) \sin(q_m n), \quad q_m := \frac{\pi m}{N+1}, \quad 1 \leq m \leq N$$

and obtain the linear Schrodinger problem

$$\mathcal{L}\hat{u}_m = \lambda_m \hat{u}_m, \quad \mathcal{L} = -\underline{m}\partial_t^2 - k(t),$$

where  $\lambda_m = 4 \sin^2\left(\frac{q_m}{2}\right)$ .

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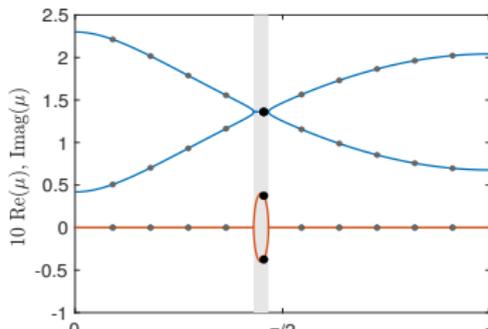
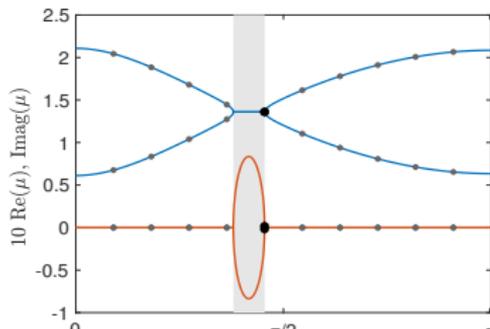
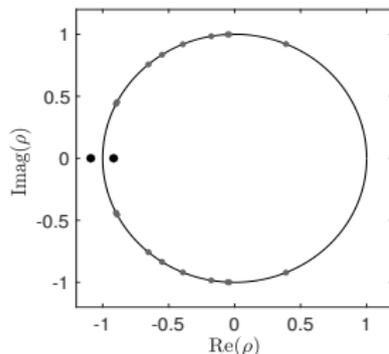
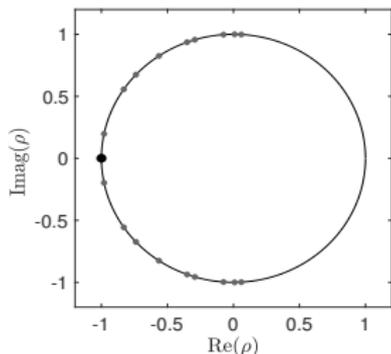
where  $\lambda_m = 4 \sin^2\left(\frac{q_m}{2}\right)$ .

The spectrum of  $\mathcal{L}$  is purely continuous in

$$\sigma(\mathcal{L}) = [\nu_0, \mu_1] \cup [\mu_2, \nu_1] \cup [\nu_2, \mu_3] \cup [\mu_4, \nu_3] \cup \dots$$

# Bifurcation theory

We are looking for a bifurcation case of  $k_0(t)$  when  $\lambda_{m_0} = \mu_1$  or  $\lambda_{m_0} = \mu_2$  for one  $m_0 \in \{1, 2, \dots, N\}$ .



## Main theorem [C. Chong, D.P., G. Schneider (2024)]

Assume two conditions (spectral assumption and nonzero normal form). Then there exists an  $\varepsilon_0 > 0$  such that for all  $\varepsilon \in (0, \varepsilon_0)$  and every  $M \in \mathbb{N}$  the FPU system possesses two generalized homoclinic solutions  $U_{\text{hom}}^{\pm}(t) : [-\varepsilon^{-M+1}, \varepsilon^{-M+1}] \rightarrow \mathbb{R}^N$  satisfying

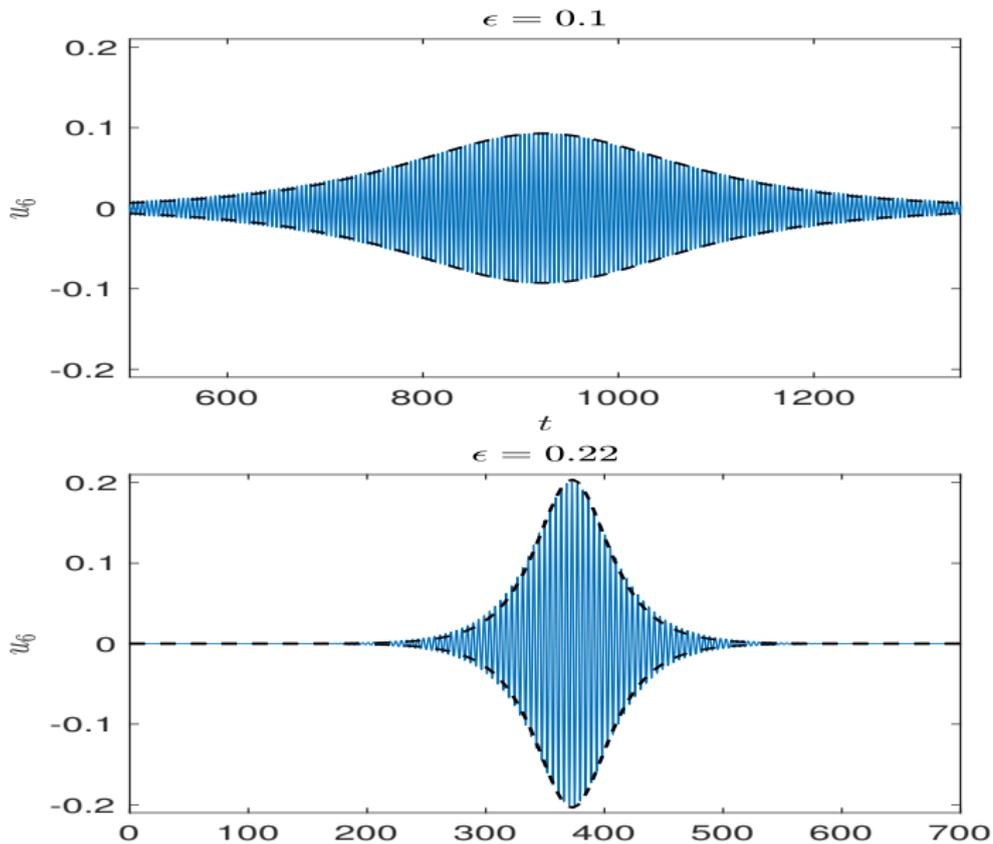
$$\sup_{t \in [-\varepsilon^{-M+1}, \varepsilon^{-M+1}]} \|U_{\text{hom}}^{\pm}(t) - \mathcal{U}^{\pm}(t)\| + \|(U_{\text{hom}}^{\pm})'(t) - (\mathcal{U}^{\pm})'(t)\| \leq C\varepsilon^{M-1}$$

where  $\mathcal{U}^{\pm}(t) : \mathbb{R} \rightarrow \mathbb{R}^N$  satisfy  $\lim_{|t| \rightarrow \infty} \|\mathcal{U}^{\pm}(t)\| + \|(\mathcal{U}^{\pm})'(t)\| = 0$  and can be approximated as

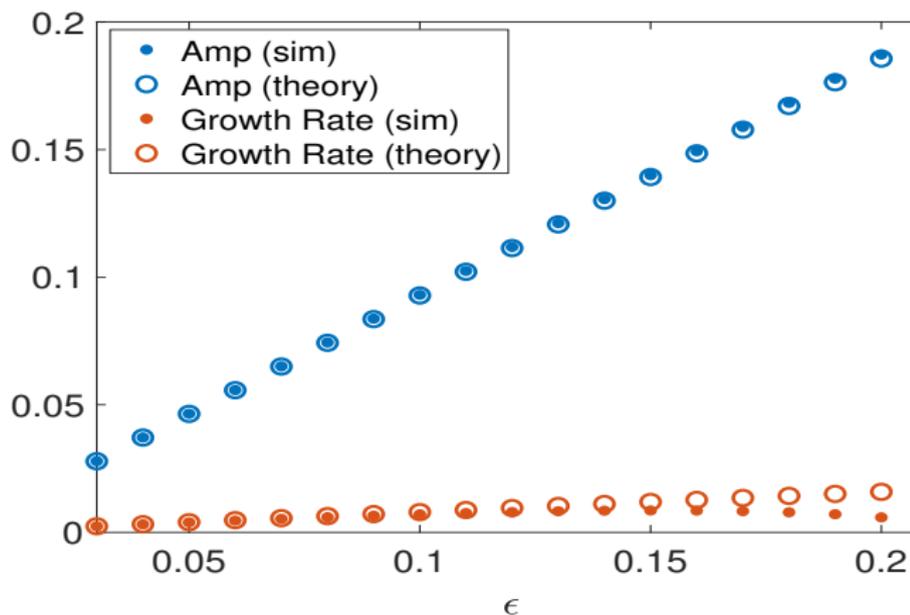
$$(\mathcal{U}^{\pm})_n(t) = \pm\varepsilon [A(\varepsilon t)\mathcal{F}(t) + \bar{A}(\varepsilon t)\bar{\mathcal{F}}(t)] \sin(q_{m_0}n) + \mathcal{O}(\varepsilon^2),$$

where  $\mathcal{F}(t+T) = -\mathcal{F}(t)$  and  $A(\tau) = \alpha \operatorname{sech}(\beta\tau)$  are uniquely defined with some  $\alpha, \beta > 0$ .

# Numerical illustration



# Comparison between normal form and numerics



# Algorithm for justification of the homoclinic solutions

## Step 1: Bifurcation setup.

Let  $k(t) = k_0(t) + \sigma\varepsilon^2$  and pick  $k_0(t)$  so that  $\lambda_{m_0} = \mu_1$  for one  $m_0 \in \{1, 2, \dots, N\}$ . This corresponds to the spectral band  $\{\lambda_1(\ell)\}_{\ell \in [0, \frac{2\pi}{T})}$  with  $\lambda_1(\ell_0) = \mu_1$  for  $\ell_0 = \frac{\pi}{T}$ . Assume no other Floquet multipliers to coincide with  $+1$  or  $-1$ .

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## Step 2: Formal derivation of the normal form. Expanding

$$u_n(t) = \varepsilon U_n^{(1)}(t) + \varepsilon^2 U_n^{(2)}(t) + \varepsilon^3 U_n^{(3)}(t) + \mathcal{O}(\varepsilon^4),$$

we select the leading order in the form

$$U_n^{(1)}(t) = A(\varepsilon t) g_1(t) \sin(q_{m_0} n),$$

where  $g_1(t + T) = -g_1(t)$  is the bifurcating mode of  $\mathcal{L}_0 g_1 = \mu_1 g_1$ .

# Algorithm for justification of the homoclinic solutions

At the order of  $\mathcal{O}(\varepsilon^2)$ , we get

$$\mathcal{L}_0 U_n^{(2)} + \Delta U_n^{(2)} = 2\underline{m}A'(\tau)g_1'(t)\sin(q_{m_0}n) + \chi_2 A(\tau)^2 g_1(t)^2 F_n^{(2)},$$

where  $\tau = \varepsilon t$  and  $F_n^{(2)} = -2\sin(q_{m_0})(1 - \cos(q_{m_0}))\sin(2q_{m_0}n)$ .

The solution for  $U_n^{(2)}(t)$  can be written in the form

$$U_n^{(2)}(t) = A'(\tau)h_1(t)\sin(q_{m_0}n) + \chi_2 A(\tau)^2 h_2(t)\sin(2q_{m_0}n),$$

where

$$\begin{aligned}(\mathcal{L}_0 - \omega^2(q_{m_0}))h_1 &= 2\underline{m}g_1'(t), \\ (\mathcal{L}_0 - \omega^2(2q_{m_0}))h_2 &= -2\sin(q_{m_0})(1 - \cos(q_{m_0}))g_1(t)^2.\end{aligned}$$

The unique solution for  $h_1(t+T) = -h_1(t)$  and  $h_2(t+T) = h_2(t)$  exists **under the spectral assumption**.

## Algorithm for justification of the homoclinic solutions

At the order of  $\mathcal{O}(\varepsilon^3)$ , we get

$$\begin{aligned}\mathcal{L}_0 U_n^{(3)} + \Delta U_n^{(3)} &= \sigma U_n^{(1)} + 2m\partial_\tau \partial_t U_n^{(2)} + m\partial_\tau^2 U_n^{(1)} \\ &+ 2\chi_2 \left[ (U_{n+1}^{(1)} - U_n^{(1)})(U_{n+1}^{(2)} - U_n^{(2)}) - (U_n^{(1)} - U_{n-1}^{(1)})(U_n^{(2)} - U_{n-1}^{(2)}) \right] \\ &- \chi_3 \left[ (U_{n+1}^{(1)} - U_n^{(1)})^3 - (U_n^{(1)} - U_{n-1}^{(1)})^3 \right].\end{aligned}$$

Projection to the mode  $\sin(q_{m_0}n)$  yields the cubic normal form:

$$\frac{1}{2}\lambda_1''(\ell_0)A''(\tau) + \sigma A(\tau) + \chi A(\tau)^3 = 0,$$

where  $\lambda_1''(\ell_0)$  is the band curvature at  $\lambda_1(\ell_0) = \mu_1$ , where  $\lambda_1'(\ell_0) = 0$ , and  $\chi \neq 0$  **under the normal form assumption**.

# Algorithm for justification of the homoclinic solutions

**Step 3: Justification of the normal form.** The normal form theorem near the double period bifurcation (Iooss–Adelmeyer, 1998) after diagonalization, near-identity transformations, and the use of reversibility.

# Conclusion

- ▷ Generalized breathers have been considered either as the time-periodic and space-localized pulses or as the time-localized and space-periodic orbits.
- ▷ These solutions can be recovered in the spatial dynamical systems on a long but finite spatial scale.
- ▷ Numerical experiments do not often distinguish between true breathers and generalized modulating pulses.

**MANY THANKS FOR YOUR ATTENTION!**

**BEST WISHES TO MICHAEL!!!**